

Stochastic feedback control of quantum transport to realize a dynamical ensemble of two nonorthogonal pure states

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A Markovian open quantum system which relaxes to a unique steady state ρ_{ss} of finite rank can be decomposed into a finite physically realizable ensemble (PRE) of pure states. That is, as shown by Karasik and Wiseman [Phys. Rev. Lett. **106**, 020406 (2011)], in principle there is a way to monitor the environment so that in the long time limit the conditional state jumps between a finite number of possible pure states. In this paper we show how to apply this idea to the dynamics of a double quantum dot arising from the feedback control of quantum transport, as previously considered by one of us and co-workers [Phys. Rev. B **84**, 085302 (2011)]. Specifically, we consider the limit where the system can be described as a qubit, and show that while the control scheme can always realize a two-state PRE, in the incoherent tunneling regime there are infinitely many PREs compatible with the dynamics that cannot be so realized. For the two-state PREs that are realized, we calculate the counting statistics and see a clear distinction between the coherent and incoherent regimes.

I. INTRODUCTION

Applications of quantum feedback control have been demonstrated in a variety of systems, including quantum dots [1, 2], superconducting qubits [3, 4], and trapped ions [5, 6]. In particular, the ability to monitor the environment of a quantum system and to act on it based on the measurement results has been shown to be a powerful tool for controlling quantum dynamics. One of the most interesting applications of quantum feedback control is the realization of a dynamical ensemble of pure states. This was first proposed by Karasik and Wiseman [7] and later demonstrated experimentally [8]. In their work, they showed that a Markovian open quantum system which relaxes to a unique steady state ρ_{ss} of finite rank can be decomposed into a finite physically realizable ensemble (PRE) of pure states. That is, in principle there is a way to monitor the environment so that in the long time limit the conditional state jumps between a finite number of possible pure states. In this paper we show how to apply this idea to the dynamics of a double quantum dot arising from the feedback control of quantum transport, as previously considered by one of us and co-workers [9]. Specifically, we consider the limit where the system can be described as a qubit, and show that while the control scheme can always realize a two-state PRE, in the incoherent tunneling regime there are infinitely many PREs compatible with the dynamics that cannot be so realized. For the two-state PREs that are realized, we calculate the counting statistics and see a clear distinction between the coherent and incoherent regimes.

how this can be done is discussed in Sec. II. In Sec. III we discuss the counting statistics of the system and show that there is a clear distinction between the coherent and incoherent regimes. In Sec. IV we discuss the implications of our results for quantum feedback control and for the realization of a dynamical ensemble of pure states. Finally, in Sec. V we conclude.

II. TRACKING THE STATE OF A QUBIT USING A BIT

Consider a qubit system S with Hilbert space \mathcal{H}_S and a bit system B with Hilbert space \mathcal{H}_B . The total system $S+B$ is initially in a state ρ_0 .

$$\dot{\rho} = -i[\hat{H}, \rho] + \sum_l \mathcal{D}[c_l]\rho \equiv \mathcal{L}\rho, \quad (1)$$

where $\mathcal{D}[\hat{O}]\bullet = \hat{O}\bullet\hat{O}^\dagger - 1/2\{\hat{O}^\dagger\hat{O}, \bullet\}$ and $\mathcal{L} = -i[\hat{H}, \bullet] + \sum_l \mathcal{D}[c_l]\bullet$.

The bit system B is initially in a state ρ_B and evolves according to the Lindblad equation $\dot{\rho}_B = \mathcal{L}_B \rho_B$.

$$\mathcal{L} = S[\hat{H}'] + \sum_{l=1}^L \mathcal{J}[c_l] \quad (2)$$

where $S[\hat{H}']\bullet = (-i\hat{H}')\bullet + \bullet(i\hat{H}'^\dagger)$ and $\mathcal{J}[c]\bullet = c\bullet c^\dagger$.

$$\hat{H}' = \hat{H} - \frac{i}{2} \sum_{l=1}^L \hat{c}_l^\dagger \hat{c}_l \quad (3)$$

The bit system B is initially in a state ρ_B and evolves according to the Lindblad equation $\dot{\rho}_B = \mathcal{L}_B \rho_B$.

$$\rho(t) = \mathcal{M}(t)\rho(0) = e^{\mathcal{L}t}\rho(0). \quad (4)$$

The evolution of the bit system B is given by $\mathcal{M}(t) = \sum_{n=0}^{\infty} \mathcal{M}^{(n)}(t)$.

$$\mathcal{M}^{(n)}(t) = \int_0^t dt_n \int_0^{t_n} dt_{n-1} \cdots \int_0^{t_2} dt_1 Q(t-t_n) \mathcal{J} \times Q(t_n-t_{n-1}) \mathcal{J} \cdots Q(t_2-t_1) \mathcal{J} Q(t_1), \quad (5)$$

where $Q(t) = e^{tS[\hat{H}']}$ and $S[\hat{H}'] = -i[\hat{H}', \bullet] + \sum_l \mathcal{D}[c_l]\bullet$.

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$$\hat{c}_l \rightarrow \hat{c}_m = \sum_{l=1}^L \tilde{U}_{ml} \hat{c}_l + \beta_m, \quad (6)$$

$$\hat{H} \rightarrow \hat{H}' = \hat{H} - \frac{i}{2} \sum_{m=1}^M (\beta_m^* \hat{c}_m - \beta_m \hat{c}_m^\dagger), \quad (7)$$

where β_m and $\tilde{U}_{ml} \in \mathbb{C}^{M \times L}$.

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\tilde{U}

$\{\beta_l\}, \{M_{lk}\}$

$\mathcal{L}\rho_{ss} = 0$

If ρ_{ss} is a fixed point of \mathcal{L} , then $\mathcal{L}\rho_{ss} = 0$.

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preferred ensemble fact⁹.

$\{\beta_m\}, \{\tilde{U}_{ml}\}$

¹⁰, \tilde{U}

¹⁰ \tilde{U}

$$\vec{r}' = A\vec{r} + \vec{b}, \quad (8)$$

where A is a 3×3 matrix and \vec{b} is a vector.

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A and $\{\beta_k, \vec{r}_k\}_{k=\pm}$

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$$\vec{r}_k = \vec{r}_{ss} - k\alpha_k \vec{e}_v, \quad \text{?}$$

$$p_k = \frac{1}{2} \left[1 - \frac{k\vec{r}_{ss} \cdot \vec{e}_v}{\sqrt{1 - \|\vec{r}_{ss}\|^2 + (\vec{r}_{ss} \cdot \vec{e}_v)^2}} \right]. \quad \text{?}$$

$$\vec{e}_v = \frac{k\vec{r}_{ss} \cdot \vec{e}_v + \sqrt{1 - \|\vec{r}_{ss}\|^2 + (\vec{r}_{ss} \cdot \vec{e}_v)^2}}{\|\vec{r}_+ - \vec{r}_-\|} \quad A, \alpha_k =$$

III. STATE STABILIZATION OF A QUBIT USING FEEDBACK CONTROL

Highly relevant to the study of quantum control and quantum information processing, particularly in the context of quantum dot systems and feedback control. The following text discusses the state stabilization of a qubit using feedback control, drawing on references 8, 14, 21-29, 34, and 35,36.

8. A. B. ... 21-29. R. ... 14. A. ... 34. ... 35,36. ...

at most ...

$\mu_L \rightarrow \infty, \mu_R \rightarrow -\infty$...

ϵ_L and ϵ_R ...

$|\emptyset\rangle \equiv |N_L, N_R\rangle$... N_d ... $d \in \{R, L\}$

$|L\rangle \equiv |N_L + 1, N_R\rangle$, ...

$|R\rangle \equiv |N_L, N_R + 1\rangle$, ...

$|\emptyset\rangle \rightarrow |L\rangle$... γ_L and γ_R ...

2,34. ...

$$\hat{H} = \frac{1}{2}\Delta\hat{\sigma}_z + T_c\hat{\sigma}_x, \quad \text{?}$$

$\equiv \epsilon_L - \epsilon_R$... T_c ...

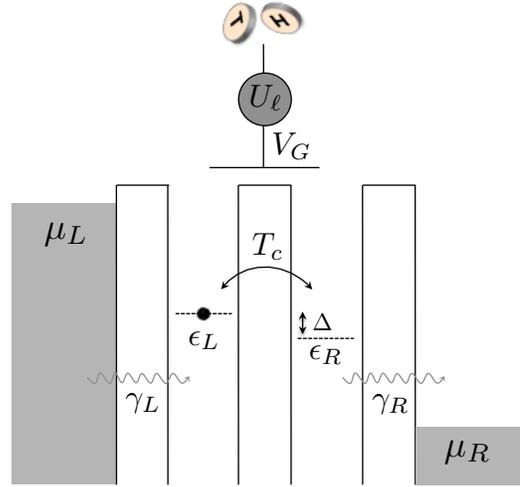
$$\sigma_z = |L\rangle\langle L| - |R\rangle\langle R|, \quad \text{30,31, in}$$


FIG. 1. Stochastic feedback control of a double quantum dot. Flow of one excess electron is monitored when it tunnels into the left dot at rate γ_L (e.g. by a QPC, not shown). A unitary control operation (which can be implemented for example with gate voltages V_G) then rotates the state of the system into one of two (randomly chosen) desired states. Here T_c is the coupling strength between the dots, Δ is the detuning, γ_R is the tunneling rate out of the right dot, and $\mu_{L(R)}$ are chemical potentials of the leads.

$\hat{\sigma}_x = |L\rangle\langle R| + |R\rangle\langle L|$ $\Delta = 0$...

$$\hat{c}_1 = \sqrt{\gamma_L}|L\rangle\langle\emptyset|, \quad \hat{c}_2 = \sqrt{\gamma_R}|\emptyset\rangle\langle R|. \quad \text{?}$$

... (??) ... (??) ...

$$\hat{H}' = -i\frac{\gamma_L}{2}|\emptyset\rangle\langle\emptyset| + \sum_{\ell=\pm} \epsilon_\ell|\phi_\ell\rangle\langle\tilde{\phi}_\ell|, \quad \text{?}$$

... (??) ... (??) ...

$$|\phi_\ell\rangle = \frac{(i\gamma_R + \ell\kappa)|L\rangle + T_c|R\rangle}{\sqrt{6 T_c^2 + |i\gamma_R + \ell\kappa|^2}}, \quad \text{?}$$

$$\epsilon_\ell = -\frac{1}{4}(i\gamma_R + \ell\kappa), \quad \kappa = \sqrt{6 T_c^2 - \gamma_R^2}. \quad \text{?}$$

... (??) ... (??) ...

$$\langle\tilde{\phi}_\ell| \hat{H}' |\phi_\ell\rangle = \epsilon_\ell, \quad \langle\tilde{\phi}_\ell| \neq \langle\phi_\ell|. \quad \text{?}$$

... (??) ... (??) ...

14, ...

30,31, in

32,33

$$|L\rangle, \text{ state}$$

$$\mathcal{J}[c_1]|\emptyset\rangle\langle\emptyset| = \gamma_L|L\rangle\langle L|. \quad \S$$

$$\hat{H}', \text{ is } |\phi_\ell\rangle^{14}. \quad \text{H}$$

$$V_G, \text{ is } \quad \text{H}$$

$$\hat{U}_\ell|L\rangle = |\phi_\ell\rangle. \quad \text{I}$$

$$\rho_\ell = |\phi_\ell\rangle\langle\phi_\ell| \text{ is } \quad \text{H}$$

$$S[\hat{H}']\rho_\ell \approx \mathfrak{S}(\varepsilon_\ell)\rho_\ell. \quad \S$$

$$\mathcal{J}[c_2]\rho_\ell = \gamma_R^\ell|\emptyset\rangle\langle\emptyset|, \quad \text{H}$$

$$\gamma_R^\ell \equiv -2\mathfrak{S}(\varepsilon_\ell) \quad \text{H}$$

$$\mathcal{H}^3 \equiv \left\{ \begin{array}{l} |\emptyset\rangle, |\phi_-\rangle, |\phi_+\rangle \\ \ell \text{ (} - \text{)} \end{array} \right\} \quad \text{H}$$

$$\gamma_L \text{ and } \gamma_R \quad \text{H}$$

$$\rho_{\text{ss}} = \frac{1}{2\gamma_L + \gamma_R^\ell} (\gamma_R^\ell|\emptyset\rangle\langle\emptyset| + \gamma_L\rho_\ell). \quad \text{H}$$

$$\gamma_L \gg \gamma_R, T_c, \text{ is } \quad \text{H}$$

$$|\emptyset\rangle\langle\emptyset| \text{ is } \quad \rho_\ell \text{ is } \quad \text{H}$$

$$U_\ell \text{ is } \quad \text{H}$$

$$\rho_\ell = |\phi_\ell\rangle\langle\phi_\ell|, \text{ is } \quad U_\ell \text{ is } \quad \text{H}$$

$$|\phi_\pm\rangle \text{ is } \quad \text{H}$$

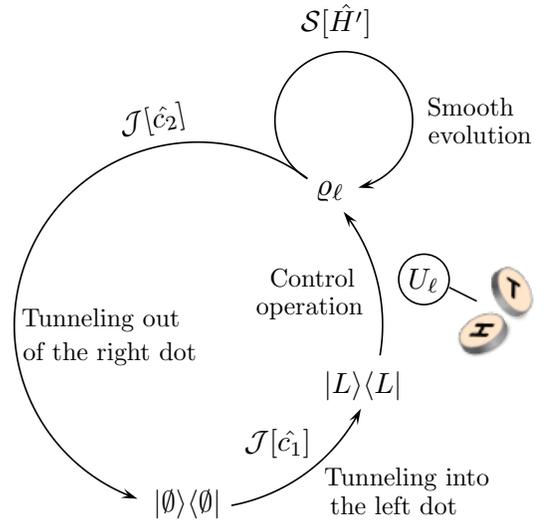


FIG. 2. A schematic representation of the state evolution of the DQD.

IV. STOCHASTIC FEEDBACK CONTROL OF THE DQD

$$\hat{c}_1 \rightarrow \hat{c}'_1 = \hat{U}_\ell \hat{c}_1 = \sqrt{\gamma_L} |\phi_\ell\rangle\langle\emptyset| \quad \text{H}$$

$$\dot{\rho} = -i[\hat{H}, \rho] + (D[\hat{c}'_1] + D[c_2])\rho. \quad \text{H}$$

$$D \equiv \text{H}$$

$$\{|L\rangle, |R\rangle\}, \text{ is } \quad \rho \text{ is } \quad \text{H}$$

$$\dot{\rho} = -i[\hat{H}, \rho] + D[c_\ell]\rho, \quad \text{H}$$

$$\hat{c}_\ell = \sqrt{\gamma_R} \hat{U}_\ell |L\rangle\langle R| = \sqrt{\gamma_R} |\phi_\ell\rangle\langle R|. \quad \text{H}$$

$$|\phi_\ell\rangle \text{ is } \quad \text{H}$$

$$\hat{H}' = \hat{H} - \frac{i}{2} \hat{c}_\ell^\dagger \hat{c}_\ell = \varepsilon_\ell |\phi_\ell\rangle\langle\phi_\ell|. \quad \text{H}$$

$$|\phi_\pm\rangle \text{ is } \quad \text{H}$$

ρ_{\pm} is the steady state density matrix of the system, which is a function of the system Hamiltonian H_S and the system-environment interaction H_{SE} . The system-environment interaction is assumed to be weak, so that the system and environment can be treated as two independent systems. The system Hamiltonian is assumed to be a two-level system, and the environment is assumed to be a harmonic oscillator. The system-environment interaction is assumed to be a linear coupling between the system and the environment.

> In

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ρ_{\pm} is the

$$\sum_{\ell} \rho_{\ell} = \rho_{\pm}$$

$$\hat{U}_{\pm}$$

$$\tau_{\ell} \propto (\gamma_R \rho_{\ell}^{RR})^{-1},$$

⊗

$$\hat{U}_{\ell}, \text{ w}$$

w

$$\rho_{\ell}^{RR} = \langle R | \rho | R \rangle_{\ell} = \frac{1 - \langle \hat{\sigma}_z \rangle_{\ell}}{2}.$$

⊗

$$\dot{\rho} = -i[\hat{H}, \rho] + \sum_{\ell=\pm} \rho_{\ell} \mathcal{D}[c_{\ell}] \rho,$$

⊗

??) $\langle \hat{\sigma}_z \rangle_{\pm}$

$$\langle \hat{\sigma}_z \rangle_{\pm} = \text{Tr}[\hat{\sigma}_z \rho_{\pm}]$$

$$\tau_{\ell} \approx 1/\gamma_R$$

⊗

$$\rho_{\text{ss}} = \sum_{\ell=\pm} p_{\ell} \rho_{\ell}.$$

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$$\rho_{\ell} = p_{\ell} \rho_{\pm}$$

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A. Coherent tunneling ($\gamma_R < 4T_c$)

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$$|L\rangle \text{ and } |R\rangle$$

$$\rho_{-} = \rho_{+} = \rho_{\pm}$$

$$\vec{r}_{\ell} = \left(-\ell \frac{\kappa}{4T_c}, -\frac{\gamma_R}{4T_c}, 0 \right), \quad \gamma_R < 4T_c.$$

A

B. Incoherent tunneling ($\gamma_R > 4T_c$)

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$$\kappa = i\kappa \text{ and } \kappa = i\kappa$$

$$\vec{r}_{\ell} = \left(0, -\frac{4T_c}{\gamma_R}, -\ell \frac{\tilde{\kappa}}{\gamma_R} \right), \quad \gamma_R > 4T_c.$$

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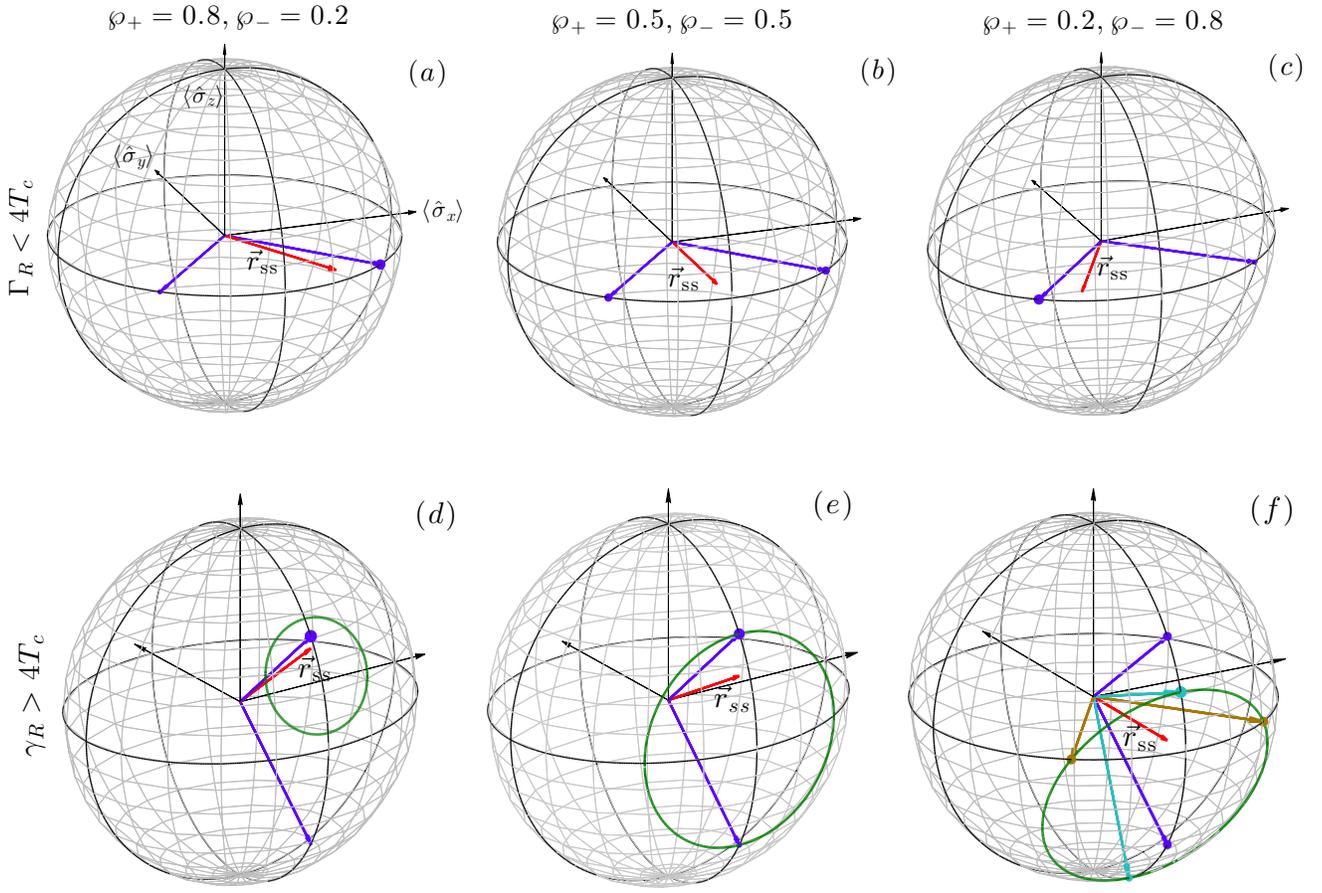


FIG. 3. (Color online). Bloch representation of TSEs. The top row shows, for $\gamma_R = 3, T_c = 1$, Bloch vectors of two-state hopping for three different probabilities defining the stochastic feedback: (a) $\varphi_+ = 0.8, \varphi_- = 0.2$, (b) $\varphi_+ = 0.5, \varphi_- = 0.5$, and (c) $\varphi_+ = 0.2, \varphi_- = 0.8$. Blue arrows (dark arrows in the azimuthal plane) represent the state vectors of the TSE with associated probabilities p_ℓ Eq. (10), indicated by the volume of the sphere at the tip of each vector. The steady state \vec{r}_{ss} is depicted by a red arrow. In this regime, the probabilities φ_ℓ are equal to the probabilities p_ℓ that the system is found in a particular state of the TSE. The bottom row shows TSEs for $\gamma_R = 5, T_c = 1$ for the same control probabilities as in the top row. Here, in contrast, in addition to the eigenvectors of the effective Hamiltonian \hat{H}' , shown by blue arrows (dark arrows in the polar plane), an infinite number of other two-state TSEs exist. The solid green circle depicts the locus of them. By comparing this circle in (d), (e), and (f) it is clear that increasing φ_+ shrinks its radius such that at $\varphi_+ = 1$ it eventually collapses to a single point. In (f) we plot the states of two other TSEs each corresponding to a real eigenvector of A shown in light brown (in the azimuthal plane) and cyan (dark arrows in the polar plane). In the bottom row, φ_ℓ and p_ℓ are entirely different because the latter is a function of the lifetimes of states in the right dot, Eq. (??).

$$p_\ell = \frac{\varphi_\ell \tau_\ell}{\sum_{j=\pm} \varphi_j \tau_j}, \quad \varphi_\ell \text{ is}$$

$$\tau_\ell = \frac{1}{\gamma_R + \ell \tilde{\kappa}}, \quad \tau_1 = \tau_2, \quad \gamma_R \neq T_c,$$

$$\vec{r}_{ss} = \vec{r}_\pm = (0, -1, 0)$$

with
 the
 time

ρ_L

Physical meaning of the other TSEs

What is an

observable

operator

??)

28,29

$$|\Psi\rangle \propto \sum_r |\phi_{\ell r}\rangle |\xi_r\rangle.$$

r

r

$|\phi_{\pm}\rangle$

??)

37,38

39

V. COUNTING STATISTICS OF QUANTUM TRANSPORT

with

the

time

operator

$$P(n, t) = \langle \rho^{(n)}(t) \rangle$$

t

$$\rho^{(n)}(t)$$

e.g.

??)

$$\rho(t) = \sum_{n=0}^{\infty} \rho^{(n)}(t)$$

$$\dot{\rho}^{(n)} = S \rho^{(n)} + \sum_{\ell=\pm} \varphi_{\ell} \mathcal{J}[\rho_{\ell}] \rho^{(n-1)}.$$

with

the

field

χ

$$\rho(\chi) = \sum_n e^{in\chi} \rho^{(n)}$$

$$\dot{\rho}(\chi) = (S + \sum_{\ell=\pm} \varphi_{\ell} \mathcal{J}[\rho_{\ell}] e^{i\ell\chi}) \rho(\chi) \equiv \mathcal{L}(\chi) \rho(\chi).$$

with

$$\mathcal{F}(\chi, t)$$

32

$$e^{\mathcal{F}(\chi, t)} = \sum_{N=0}^{\infty} P(N, t) e^{iN\chi}$$

with

the

operator

$$\mathcal{F}(\chi, t) = \langle \mathcal{L}(\chi)^t \rho(0) \rangle.$$

$t \rightarrow \infty$

$$\mathcal{L}(\chi)$$

$$\mathcal{F}(\chi, t) = \lambda_0(\chi) t$$

with

the

operator

$$\langle S^{(n)} \rangle = \frac{d}{dt} \frac{\partial^n}{\partial (i\chi)^n} \mathcal{F}(\chi, t) |_{\chi=0, t \rightarrow \infty} = \frac{\partial^n}{\partial (i\chi)^n} \lambda_0(\chi) |_{\chi=0}.$$

$$\langle S^{(1)} \rangle$$

32

$$F^{(n)} = \frac{\langle S^{(n)} \rangle}{\langle S^{(1)} \rangle^n}.$$

 $n = 4$
 γ_R/T_c
 θ, ϑ_c
 φ_{\pm}
 $\gamma_R \leq 4T_c$
 $F^{(n)} = 1$
 T_c
 $\varphi_+ = 1$
vice versa

VI. CONCLUSION

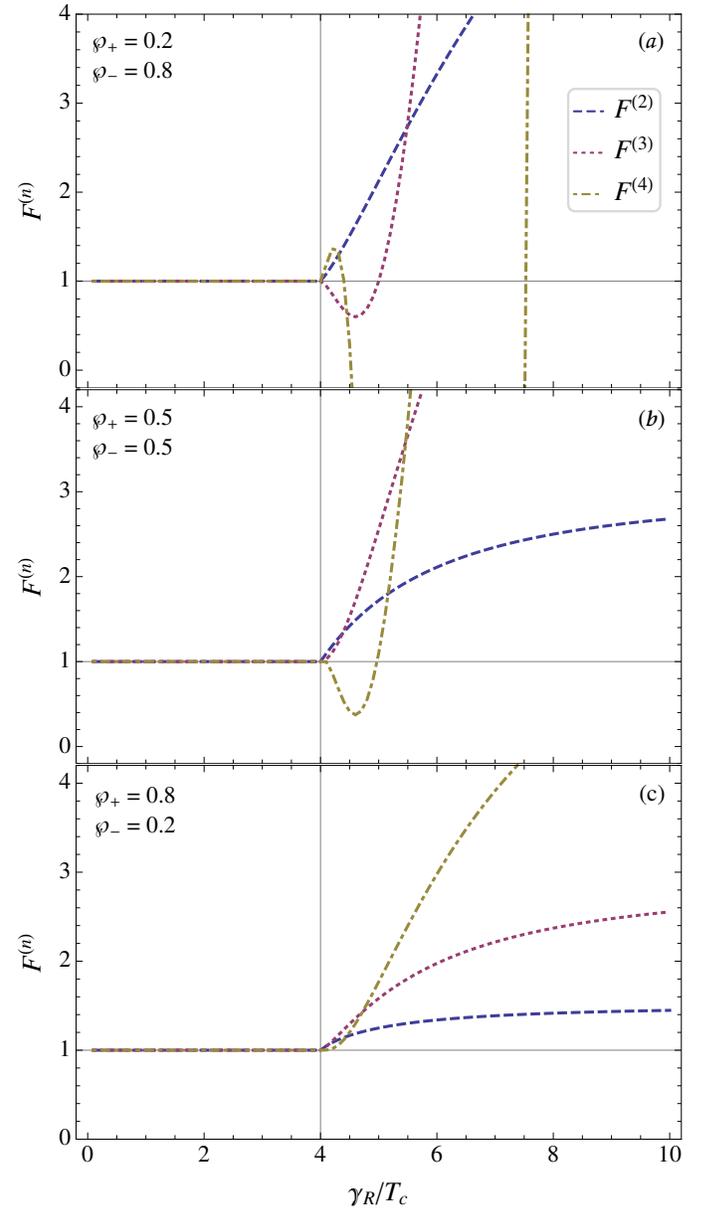
 $10,40$
 $41,42$
 43


FIG. 4. (Color online). The value of Fano factors $F^{(n)}$, Eq. (??), for the DQD versus the ratio of tunneling rates γ_R/T_c : $n = 2$ (blue dashed), $n = 3$ (pink dotted), and $n = 4$ (light brown dashed-dotted). Three different sets of probabilities are shown (a) $\varphi_+ = 0.2, \varphi_- = 0.8$, (b) $\varphi_+ = 0.5, \varphi_- = 0.5$, and (c) $\varphi_+ = 0.8, \varphi_- = 0.2$. As long as $\gamma_R \leq 4T_c$ all Fano factors are equal to one no matter what value is assigned to φ_{\pm} . This is correspond to the Poissonian statistics of the current which is independent of the order of the current correlation. In contrast, as γ_R becomes larger than $4T_c$ Fano factors depend on the probabilities φ_{\pm} to the extent that $F^{(n)} = 1$ only holds if and only if $\varphi_+ = 1$ and $\varphi_- = 0$, or *vice versa*.

$$\hat{H}'_{\text{eff}}$$

44

45

 φ_ℓ in

46

ACKNOWLEDGEMENT

Appendix A: Supplemental Material

1. Adiabatic elimination of the null state

47

$\rho = \varrho + \delta|\emptyset\rangle\langle\emptyset|$

$$\rho = \varrho + \delta|\emptyset\rangle\langle\emptyset| \quad \mathbb{A}$$

$\delta = O(\gamma_R/\gamma_L)$

$$\begin{aligned} \dot{\delta} &= \langle\emptyset|\dot{\rho}|\emptyset\rangle \\ &= -\gamma_L\delta + \gamma_R\langle R|\varrho|R\rangle, \end{aligned} \quad \mathbb{A}$$

$$??) \quad \gamma_L \gg \gamma_R$$

$$\delta \approx \frac{\gamma_R}{\gamma_L} \langle R|\varrho|R\rangle. \quad \mathbb{A}$$

$\dot{\varrho} = \hat{\Pi}_{\text{qb}} \dot{\rho} \hat{\Pi}_{\text{qb}}$

$$\dot{\varrho} = \hat{\Pi}_{\text{qb}} \dot{\rho} \hat{\Pi}_{\text{qb}} \quad \mathbb{A}$$

$\hat{\Pi}_{\text{qb}} = |L\rangle\langle L| + |R\rangle\langle R|$

$$\begin{aligned} \dot{\varrho} &= -i[H, \varrho] + \gamma_R|\phi_\ell\rangle\langle\phi_\ell|R\varrho|R\rangle - \\ &\quad \frac{\gamma_R}{2}(|R\rangle\langle R|\varrho + \varrho|R\rangle\langle R|) \\ &= -i[H, \varrho] + \mathcal{D}[c_\ell]\varrho. \end{aligned} \quad \mathbb{A}$$

2. Bloch equations and control parameters

A and b

$$A_{11} = -2\gamma_R \sum_{\ell=\pm} \varphi_\ell (|u_y^\ell|^2 + |u_z^\ell|^2), \quad \mathbb{A}$$

$$\begin{aligned} A_{12} &= \gamma_R \sum_{\ell=\pm} \varphi_\ell \left[(u_x^\ell u_y^{\ell*} + u_x^{\ell*} u_y^\ell) - \right. \\ &\quad \left. i(u_z^\ell w^{\ell*} - u_z^{\ell*} w^\ell) \right] - \Delta, \end{aligned} \quad \mathbb{A}$$

$$\begin{aligned} A_{13} &= \gamma_R \sum_{\ell=\pm} \varphi_\ell \left[(u_x^\ell u_z^{\ell*} + u_x^{\ell*} u_z^\ell) + \right. \\ &\quad \left. i(u_y^\ell w^{\ell*} - u_y^{\ell*} w^\ell) \right], \end{aligned} \quad \mathbb{A}$$

$$\begin{aligned} A_{21} &= \gamma_R \sum_{\ell=\pm} \varphi_\ell \left[(u_x^\ell u_y^{\ell*} + u_x^{\ell*} u_y^\ell) + \right. \\ &\quad \left. i(u_z^\ell w^{\ell*} - u_z^{\ell*} w^\ell) \right] - \Delta, \end{aligned} \quad \mathbb{A}$$

$$A_{22} = -2\gamma_R \sum_{\ell=\pm} \varphi_\ell (|u_x^\ell|^2 + |u_z^\ell|^2), \quad \mathbb{A}$$

$$\begin{aligned} A_{23} &= \gamma_R \sum_{\ell=\pm} \varphi_\ell (u_y^\ell u_z^{\ell*} + u_y^{\ell*} u_z^\ell) - \\ &\quad i(u_x^\ell w^{\ell*} - u_x^{\ell*} w^\ell) - 2T_c, \end{aligned} \quad \mathbb{A}$$

$$A_{31} = \gamma_R \sum_{\ell=\pm} \wp_{\ell} \left[(u_x^{\ell} u_z^{\ell*} + u_x^{\ell*} u_z^{\ell}) - i(u_y^{\ell} w^{\ell*} - u_y^{\ell*} w^{\ell}) \right],$$

$$A_{32} = \gamma_R \sum_{\ell=\pm} \wp_{\ell} (u_y^{\ell} u_z^{\ell*} + u_y^{\ell*} u_z^{\ell}) + i(u_x^{\ell} w^{\ell*} - u_x^{\ell*} w^{\ell}) - 2 T_c,$$

$$A_{33} = -2\gamma_R \sum_{\ell=\pm} \wp_{\ell} (|u_x^{\ell}|^2 + |u_y^{\ell}|^2).$$

d

$$b_1 = i 2\gamma_R \sum_{\ell=\pm} \wp_{\ell} (u_y^{\ell} u_z^{\ell*} - u_y^{\ell*} u_z^{\ell}),$$

$$b_2 = i 2\gamma_R \sum_{\ell=\pm} \wp_{\ell} (u_z^{\ell} u_x^{\ell*} - u_z^{\ell*} u_x^{\ell}),$$

$$b_3 = i 2\gamma_R \sum_{\ell=\pm} \wp_{\ell} (u_x^{\ell} u_y^{\ell*} - u_x^{\ell*} u_y^{\ell}).$$

f

g

$$u^{\ell} \in \{u_x^{\ell}, u_y^{\ell}, u_z^{\ell}, w^{\ell}\}$$

$$u_x^{\ell} = \frac{1}{2} \left[\wp (\vartheta_c^{\ell}/2) - i \mathfrak{h} (\vartheta_c^{\ell}/2) \wp (\theta^{\ell}) \right],$$

$$u_y^{\ell} = i u_x^{\ell},$$

$$u_z^{\ell} = \frac{i}{2} \mathfrak{h} (\vartheta_c^{\ell}/2) \mathfrak{h} (\theta^{\ell}),$$

$$w^{\ell} = -u_z^{\ell}.$$

Substituting
the expressions
for the
coefficients

$$\theta^{\ell} \text{ and } \vartheta_c^{\ell} \text{ by}$$

$$\hat{U}_{\ell} = e^{-i\vartheta_c^{\ell} \vec{n}_{\ell} \cdot \vec{\sigma}/2},$$

we obtain

$$\mathfrak{h} (\theta^{\ell}, 0, \wp (\theta^{\ell})) \mathfrak{h} (\vartheta_c^{\ell}, \mathfrak{h} (\vartheta_c^{\ell}), \mathfrak{h} (\theta_c^{\ell}))^{14}.$$

$$\vec{n}_{\ell} =$$

$$\gamma_R < 4T_c \text{ h}$$

$$\theta^{\ell} = \left(\frac{\ell \kappa}{\sqrt{3} T_c^2 - \gamma_R^2} \right),$$

$$\vartheta_c^{\ell} = \left(\frac{\gamma_R}{\sqrt{3} T_c} \right),$$

for $\gamma_R > 4T_c$

we

$$\theta^{\ell} = \pi/2,$$

$$\vartheta_c^{\ell} = \left(\frac{4T_c}{(\gamma_R + \ell \tilde{\kappa})} \right).$$

for
 $\pi/2$

$$\gamma_R \neq T_c$$

$$\theta^{\ell} = \vartheta_c^{\ell} =$$

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