

A Computer-Aided Detection of EEG Seizures in Infants: A Singular-Spectrum Approach and Performance Comparison

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Abstract—This paper presents a scalp electroencephalogram (EEG) seizure detection scheme based on singular spectrum analysis (SSA) and Rissanen minimum description length (MDL) model-order selection (SSA-MDL). Preprocessing of the signals allows for the drastic reduction of the number of false alarms. Statistical performance comparison with seizure detection schemes of Gotman *et al.* and Liu *et al.* is performed on both synthetic data and real EEG seizures. Monte Carlo simulations based on synthetic infant EEG seizure data reveals some detection drawbacks on a large variety of seizure waveforms. Detection using both Monte Carlo and four real infant scalp EEG signals shows the superiority of the SSA-MDL method with an average good detection rate of $>93\%$ and false detection rate $<4\%$.

Index Terms—Detection, EEG seizure, infant, MDL, newborn, singular spectrum analysis.

I. INTRODUCTION

ABNORMALITIES in the electroencephalogram (EEG) have a good predictive value for a poor neurodevelopmental outcome in the newborn and infant [1]. Because the duration of the potential therapeutic window, for the use of neural rescue agents, is about 2–6 hours [2], automatic detection of predefined patterns have started to be investigated. Seizure EEG patterns have been studied using computerized methods. This subclass of the so-called paroxysmal-type EEG patterns has been shown to provide reliable predictive indicators for encephalopathy. In most cases, infants showing seizure have poor health outcomes and a great probability of death [3].

To the best of our knowledge, two efficient methods have been developed and thoroughly assessed for computer-aided detection of seizures in newborn and infant scalp EEG signals. The first method is based on the computation of a running autocorrelation function and was proposed by Liu *et al.* [4] (LIU). The second method, proposed by Gotman *et al.* [5] (GOTMAN), is based on the analysis of running periodograms. We would like to point out that detection of EEG events in newborn and infants cannot be performed without a close inspection of many

signals such as EEG electrocardiogram, respiratory excursions, electro-oculogram, and video. This is because daily care of babies can produce EEG waveforms that mimics typical EEG patterns, and artifacts/interferences can mask the relevant information. For these reasons, we believe that detection of EEG patterns in infants cannot be fully automated and we prefer using the terminology *computer-aided detection*.

A new seizure detection method based on singular spectrum analysis (SSA) and information theoretic-based selection of the signal subspace is designed in this paper [SSA-Rissanen minimum description length (MDL) model-order selection (SSA-MDL)]. This approach is shown to outperform the above mentioned detection schemes (LIU and GOTMAN). The motivations for using the SSA are: 1) SSA performs very well on quasi-periodic signals, which is the case for EEG seizures and 2) the use of singular-value decomposition (SVD) of the so-called trajectory matrix is highly robust to noise. The detection scheme proceeds with a preprocessing of the data, SSA and the use of Rissanen's MDL criterion [6], [7]. The preprocessing is based on a nonlinear whitening filter that spreads the spectrum of the background while keeping rhythmical features of the seizure events. The nonlinear function transform the non-Gaussian shape of the probability density function (pdf) of the EEG into a Gaussian one. This allows for the optimal use of MDL and reduces the effects of the artifacts. Using such a criterion also reduces the drawback of using subjective and data-dependent predefined threshold, typical of classical test-statistic detectors.

EEGs from newborns and infants varie from day to day and displays: 1) nonstationarity during a single recording [8]–[11]; 2) a non-Gaussian pdf [12]; 3) various artifacts; and 4) a rhythmical background EEG for which the frequency spectrum largely overlap with the seizure one. These signal characteristics may impinge on the performances of computer-based detection, and motivates the assessment of published methods. The easiest and most reliable way to do this assessment is to generate synthetic EEG signals with prescribed background and seizure. We used synthetic data of EEG seizures presented in [13].

This paper is organized as follows. Section II describes the data acquisition method. Section III presents the nonlinear non-stationary model-based EEG seizure scheme. Section IV introduces the SSA-MDL detection method, along with LIU and GOTMAN. Section V presents the results of the statistical performance analysis of LIU, GOTMAN, and SSA-MDL on synthetic data. Section VI compare the performances of the three

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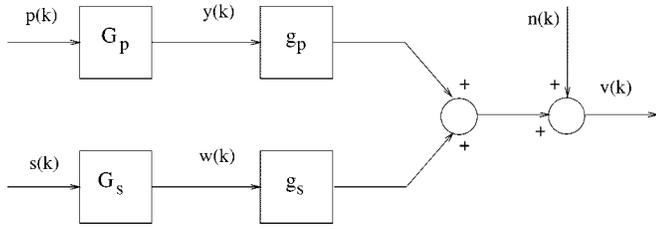


Fig. 1. Nonlinear nonstationary model of EEG seizure.

detection schemes on ten babies suffering from EEG seizures. Section VII discusses the results. Conclusions are presented in Section VIII

II. EXPERIMENTAL SETUP

The data acquisition was performed at the Royal Women's Hospital and Royal Children's Hospital, Brisbane, Australia. Between five and 20 EEG channels were recorded depending on the available recording system and the head size. Four babies from conceptual age (between five and seven weeks) to maximum six months after birth were used.

Ag–AgCl electrodes flushed with conductive gel and adhered by tape attached to the skin of the infant were used [14]. The four babies were showing signs of clinical and electrical seizures. These four recordings were visually segmented (extraction of the seizure epochs) by a neurologist from the Neurosciences Department at the Royal Children's Hospital.

The electrode placement agrees with the American EEG Society standards, while the electrode positions F1 and F2 are not true 10–20 positions, but are commonly used for babies [14]. Slow baseline fluctuations due to baby movement have been removed by using a second-order high-pass Butterworth filter with a cutoff frequency of 0.1 Hz. These signals were amplified and digitized using either the Amlab (AmLab Technologies, Lewisham, NSW, Australia) or Medelec (Oxford Instruments, U.K.) software/hardware environment. The sampling frequency was set to $F_s = 256$ Hz. EEG signals were then subsampled at $F_r = 40$ Hz to agree with GOTMAN [5] and LIU [4] detection standard.

Surface electrocardiogram (three leads), a symmetric electro-oculogram, and respiratory excursions signals were also recorded for control purposes.

III. SYNTHETIC EEG SEIZURE

In order to compare the performance of the SSA-MDL algorithm with LIU and GOTMAN, we used the EEG model proposed in [13] to generate synthetic background and seizure EEG activities. The model structure, shown in Fig. 1 and detailed in [13], is derived from a previously proposed seizure model by Roessgen *et al.* [15] who extended the model initiated by Lopes da Silva *et al.* [16] in introducing a seizure input sawtooth signal $z(t)$. An identification procedure has been examined in [13]. It is assumed throughout the text that the signals are sampled such that the continuous-time variable t is discretized as $t = k/F_r$, and we use t or k depending on the context. The pure background activity is modeled by an autoregressive moving average

(ARMA) filter $G_p(z)$ excited by a zero mean GWN $p(k)$, followed by a nonlinear function g_p . $p(k)$ is assumed to model deep brain activities in structures such as thalamus and brain stem. In parallel to this branch, an other ARMA filter $G_s(z)$ is excited by a deterministic signal $s(k)$ followed by a nonlinear function g_s . The signal $s(k)$ is a piecewise linear frequency modulated sawtooth signal [13]. The later branch is expected to represent the pure seizure activity. The sum of these two branches gives the output signal $v(k)$, which is also the measured EEG signal, and expressed by

$$v(k) = g_s[w(k)] + g_p[y(k)] + n(k) \quad (1)$$

where $y(k) = G_p(z)p(k)$ and $w(k) = G_s(z)s(k)$. A measurement noise $n(k)$, assumed to be Gaussian and white (GWN) of variance σ_n^2 and zero mean, is added. The input signals are the GWN $p(k)$ and the deterministic signal $s(t)$ expressed as

$$s(t) = z(t)e^{j2\pi f_i(t)t}, \text{ where } f_i(t) = \frac{\alpha}{2}t \quad (2)$$

$f_i(t) + f_o$ is the instantaneous frequency of $s(t)$ with $z(t)$ a sawtooth signal of period $1/f_o$. In the full model proposed in [13], $f_i(t)$ is a three-element piecewise linear function. But, for our performance comparison, a simple linear frequency modulated law is sufficient. The α parameter represents the slope of linear frequency modulation. The output signal $v(k)$ mean is set to zero and its variance normalized to unity. The two last terms on the right-hand side of (1) can be interpreted as the stochastic parts of the model and grouped as $\eta(k) = g_p[y(k)] + n(k)$ such that $v(k) = g_s[w(k)] + \eta(k)$. In most of the situations, the contribution $\eta(k)$ to the total EEG activity is less important than the pure seizure activity $g_s[w(k)]$ resulting in a relatively high seizure-to-background ratio (SBR)

$$\text{SBR} = 10 \log_{10} \frac{E[g_s^2[w(k)]]}{E[\eta^2(k)] + \sigma_n^2}. \quad (3)$$

Using SSA and model selection [17], we have estimated that $10 \text{ dB} \leq \text{SBR} \leq 30 \text{ dB}$ on 56 EEG seizure segments. Assuming the independence of $s(k)$ and $p(k)$, the signal-to-noise ratio (SNR) is given by

$$\text{SNR} = 10 \log_{10} \frac{E[g_s^2[w(k)]] + E[g_p^2[y(k)]]}{\sigma_n^2} \quad (4)$$

Fig. 2 shows recorded and synthetic background activities, and Fig. 3 shows recorded and synthetic seizure activities. We have used $\text{SNR} = 20 \text{ dB}$, $\text{SBR} = 20 \text{ dB}$. The model was identified from a baby displaying EEG seizures as in [13]. Note that the seizure signal in Fig. 3 is nonstationary and nonsymmetrical in amplitude, and the synthetic data do reproduce those behaviors.

We have selected four parameters that are mostly susceptible to influence the detection performances of LIU, GOTMAN, and SSA-MDL: the frequency f_o (especially for GOTMAN), the slope α which specifies the degree of nonstationarity, the SNR, and the SBR.

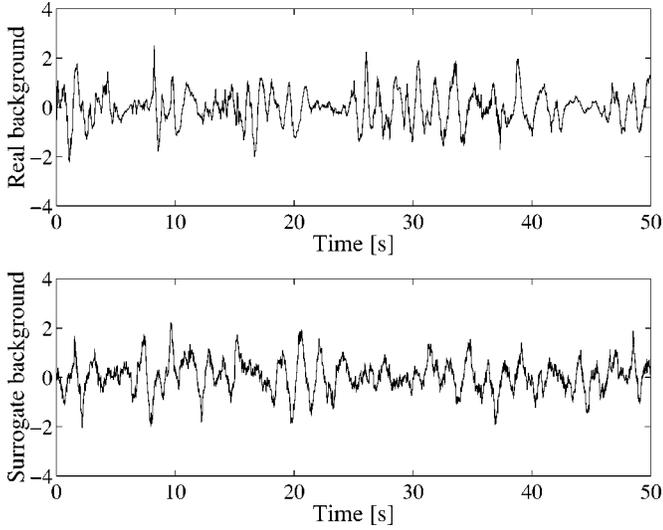


Fig. 2. Examples of real and synthetic background EEG activities.

IV. DETECTION TECHNIQUES

A. SSA-MDL Method

1) *Singular Spectrum Analysis*: Neurons and neuronal networks composing the central nervous system can discharge in both asynchronous or synchronous manners. Asynchronous discharges lead to a continuous background activity while synchronous activity leads to rhythmical patterns such as seizures [8], [18] (peaked power spectral density). It is well known that SSA is particularly suited for extracting information from quasi-periodic signals embedded in noise [19]. SSA has been used in nonlinear time series analysis with more or less success [20]–[24], but has also been shown to provide interesting results in biomedical applications [25]–[28].

The measured EEG signal $\mathbf{x} = \{x(k)\}_{k=1}^N$ is zero-meaned and normalized to have unit variance. Let $\mathbf{x}_k = [x(k), x(k+J*1), \dots, x(k+J*(n_s-1))]^T$ be a state vector in \mathbb{R}^{n_s} . The *trajectory matrix* is defined as¹

$$Z^T = [\mathbf{x}_1 \mathbf{x}_2 \cdots \mathbf{x}_{N_T}] \quad (5)$$

where $N_T = N - (n_s - 1)$. The size of the trajectory matrix Z is $N_T \times n_s$. The trajectory matrix may be viewed as a cloud of points in \mathbb{R}^{n_s} to which an n_o -dimensional ellipsoid can be fitted. The n_o principal axes of this ellipsoid are given by the eigenvectors \mathbf{e}_i of the covariance matrix $A_{zz} = (Z^T Z)/N_T$ corresponding to the n_o largest eigenvalues from $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_{n_o} \geq \dots \geq \lambda_{n_s}$. The maximum number of eigenvalues is *a priori* given by $n_s = n_o + (n_s - n_o)$. The signal \mathbf{x} can eventually be separated in two parts: *signal* (the deterministic part) and *noise* (the stochastic part) which are related to the n_o first and $n_s - n_o$ last eigenvalues. The choice of n_s is crucial and it has been shown in [19] that, for quasi-periodic signals, an upper bound is given by $n_s < \min\{F_r/\Delta B, (N/3 + 1)\}$ where ΔB is the bandwidth of the information bearing signal, for instance the seizure.

Instead of computing the sample covariance matrix A_{zz} , we performed the SVD on Z . The reason for that choice is the

¹We used a unit delay $J = 1$ while other delays may also be used.

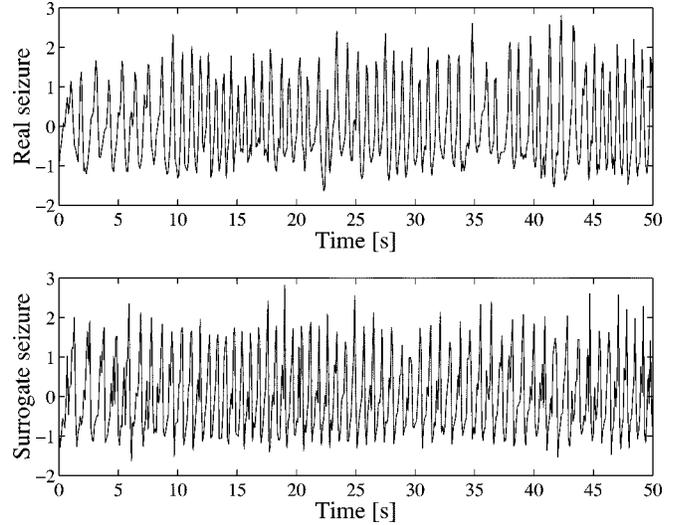


Fig. 3. Examples of real and synthetic seizure EEG activities.

robustness of the SVD against noise and its efficiency in estimating the eigenvalues of A_{zz} for short time series. The singular values σ_i of Z satisfies $\sigma_i^2 = \lambda_i$ for $i = 1, \dots, n_s$.

2) *Minimum Description Length*: The crucial question which now arises is how to determine n_o . The state space is of dimension n_s and is supposed to contain the minimal embedding space of dimension $n_o \leq n_s$. The goal now is to perform a dynamical information bearing subspace extraction; or, in other words, an optimal dimension estimation. From previous works [26]–[28], it appears that the Rissanen's MDL criterion is well adapted to the case of subspace selection in noisy environments. The formula of the MDL criterion is given by [25]

$$\begin{aligned} \text{MDL}(l, \alpha_i) = & -\ln \left[\frac{\prod_{i=l+1}^{n_s} \alpha_i^{1/(n_s-l)}}{\frac{1}{n_s-l} \sum_{i=l+1}^{n_s} \alpha_i} \right]^{N_T(n_s-l)} \\ & + n_f(l) \left(\frac{1}{2} + \ln[\gamma] \right) \\ & - \frac{n_f(l)}{l} \sum_{i=1}^l \ln \left[\alpha_i \sqrt{\frac{2}{N_T}} \right] \end{aligned} \quad (6)$$

where $\gamma = 32$ corresponds to a floating point representation, and the number of freely adjustable parameters $n_f(l)$ is given by $n_f(l) = n_s l - (l^2/2) + l/2 + 1$. In the case of the L_2 norm, $\alpha_i = \lambda_i$, while if we use the L_1 norm we should use $\alpha_i = \sigma_i$. The optimal model order n_o minimizes MDL and is given by

$$n_o = \arg \min_{l \in \{1, \dots, n_s\}} \text{MDL}(l, \alpha_i). \quad (7)$$

The following two situations can be encountered depending on the value of n_o :

- 1) if $n_o = 1$, then the signal x can be considered as a pure white noise;
- 2) if $n_o > 1$, the signal contains a nonstochastic component.

The meaning of n_o is very important in order to understand the principle of our detection technique. First, note that the min-

imum number of eigenvectors needed for representing a pure sine wave, which is in some sense the *minimal* rhythm, is two. Thus, $\lfloor n_o/2 \rfloor$ ($\lfloor x \rfloor$ is the smallest integer below x) is the number of components (or harmonics) in the signal. This component counting property of n_o has been explained in [19], [27], and [28]. Second, the usefulness of using SSA is to separate the noise part of the signal from the more deterministic part which is supposed to contain most of the information. n_o measure the complexity of the deterministic part of the signal. If the signal is composed of a pure white noise, there is no deterministic part and $n_o = 1$, otherwise $n_o > 1$.

We expect that signals for which $n_o \gg 3$ are rather complex and most probably originates from a high-dimensional system, which seems unlikely for seizure activity [27], [29]–[32].

The situation where $n_o \approx 3$ signifies that the deterministic part of the signal is quasi-periodic, or originates from a low-dimension system and may be used for detection of rhythmic activity.

3) *Preprocessing*: We want to separate the background from seizure activities as much as possible. We thus preprocess the data in order to meet the condition $n_o = 1$ in background EEG. The preprocessing makes use of the model presented in Section III. The function g_p and the filter G_p are estimated (see [13] for details) on some background EEG of the signal to be processed. The estimated inverse nonlinear function \hat{g}_p^{-1} is first applied to the measured EEG $x(k)$ in order to *Gaussianize* the data, then the estimated inverse filter \hat{G}_p^{-1} is applied to $x(k)$ and used for whitening the background EEG. The resulting signal $x_n(k)$ is

$$x_n(k) = \hat{G}_p^{-1}(z) \hat{g}_p^{-1}[x(k)] \quad (8)$$

$$= \hat{G}_p^{-1}(z) (\hat{g}_p^{-1} \circ g_s) [G_s(z)s(k)] + \tilde{n}(k) \quad (9)$$

where $s(k) = 0$ for background EEG and $\tilde{n}(k)$ is a Gaussian noise with a broadband continuous spectrum.² The pre-processed signal $x_n(k)$ thus contains a deterministic part $(\hat{G}_p^{-1}(z) (\hat{g}_p^{-1} \circ g_s) [G_s(z)s(k)])$, and a stochastic part $(\tilde{n}(k))$. Eventually, the MDL criterion will discriminates between a whitened background activity for which we expect to have $n_o = 1$ and a seizure activity with $n_o > 1$.

The SSA-MDL detection scheme proceeds in four steps which are summarized in Fig. 4 and described hereafter. First, the signal is preprocessed, then segmented using a sliding window of 10 s from which Z is constructed. The window proceed by a 1.25-s step, The SVD of Z is performed, and n_o is computed using (6) and (7) with the L_1 norm. We set a flag $F = 1$ if $n_o > 1$, and $F = 0$, otherwise. We finally stack the flags into a vector and apply a median filter of order three in order to remove isolated flags $F = 1$.

B. Gotman's Method

Gotman *et al.* [33]–[35] presented three separate methods that are intended to be used simultaneously to detect seizure. This allows each method to be developed for specific waveforms with a lower degree of variability. However, since using the three methods together causes an increase in the false detec-

²It is not perfectly white due to \hat{G}_p^{-1} .

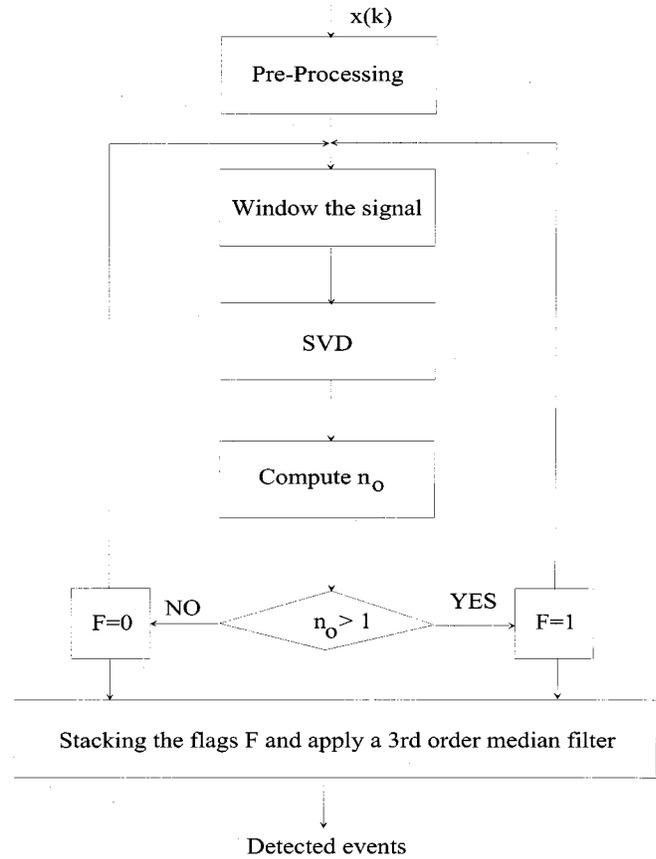


Fig. 4. Structure of the SSA-MDL detection algorithm.

tion rate (FDR), only the first method developed by Gotman will be discussed here. This method was developed specifically for seizure detection in neonates. The other two methods are modified versions of previously developed algorithms for automatic seizure detection in adults [34], [35]. The method described by Gotman [33] is based on spectral analysis and is used to detect periodic discharges. A background epoch is defined as a 20-s segment of EEG finishing 60 s before the start of the current 10-s epoch being investigated. The main advantage of a moving background epoch is that results are not dependent on the specific features of a fixed epoch. The frequency spectrum of each 10-s epoch is calculated and the following features are extracted:

- the frequency of the dominant spectral peak;
- the width of the dominant spectral peak;
- the ratio of the power in the dominant spectral peak to that of the background spectrum in the same frequency band.

The three features are used for seizure detection in each epoch. If an epoch is classified as containing seizure, a further three criteria are used to limit the number of false detections (FDs). Seizure detection is discounted if the epoch is largely nonstationary, if there is a large amount of noise power present or if it appears that an EEG lead has been disconnected.

The aim of this method is to determine if a dominant peak exists in the power spectral density estimate. This is equivalent to detecting if an EEG waveform has a dominant periodic shape in the time domain. The feature space used to classify an epoch as seizure ensures that the dominant peak of the spectrum is significant compared with the background spectrum.

C. Liu's Method

As with the above approaches, the technique of Liu *et al.* [4] assumes that the essential characteristic in newborn seizure EEG is periodicity. The amount of periodicity in the autocorrelation of short epochs of EEG data is scored and used in a rule-based algorithm to perform classification [4]. In this technique, an epoch consisting of 30 s of data is divided into five windows. Depending on the autocorrelation function of a window, up to four primary periods (T_1, \dots, T_4) are calculated for each window in an epoch. These times correspond to the times of the moment centers of the first, second, third, and fourth peaks in the autocorrelation function. The windows are then scored, whereby more evenly spaced primary periods are allocated larger scores. After each window in an epoch is scored, a rule-based detection scheme is applied to classify each epoch as *positive* or *negative*. If two or more channels of EEG data in the same epoch are *positive*, the epoch is then classified as containing seizure. For the sake of comparison with the other two techniques, we implemented Liu's method using only one channel.

V. PERFORMANCE COMPARISON ON SYNTHETIC DATA

We generated $T = 8$ min of background and seizure patterns randomly placed within T . The duration T_{SZ} of the seizure was also set randomly between 5 and 30 s. Only the number $SZ_{>10}$ of seizure patterns for which $T_{SZ} \geq 10$ s is computed. Indeed we consider rhythmical events of duration less than 5 s not classified as seizure (see [11] and references therein). Twenty Monte Carlo runs were performed for each of the parameters SBR, α , f_o ($\alpha = 0$ in that case), and SNR, within a prescribed range.

The detection signal, composed of ones and zeros, shows the occurrence of rhythmical activity. The time locations of the ones depend on the detection scheme in use. A one is said to be an *alarm*. A good detection (GD) occurs when one alarm falls within one seizure interval. Multiple occurrences of alarms during one seizure interval are considered as only one. An FD occurs when the alarm is not within any seizure interval. The total number of GDs and FDs are then counted. We define the GD rate (GDR) and FDR as

$$\text{GDR} = 100 \times \frac{\text{GD}}{SZ_{>10}} \quad (10)$$

$$\text{FDR} = 100 \times \frac{\text{FD}}{\text{GD} + \text{FD}}. \quad (11)$$

Actually, GDR is the percentage of true positive detection, and FDR is the percentage of false positive detections. Due to the use of a sliding window in each (LIU, GOTMAN, and SSA-MDL) method, ambiguity about the existence of rhythmical activity occurs at the border of seizure patterns. For this reason, we have allowed a window margin of 5 s for the LIU and SSA-MDL methods and 10 s for the GOTMAN method to account for method-dependent border effects. The window margin is greater for GOTMAN because this method uses a wider sliding window (see Section IV-B).

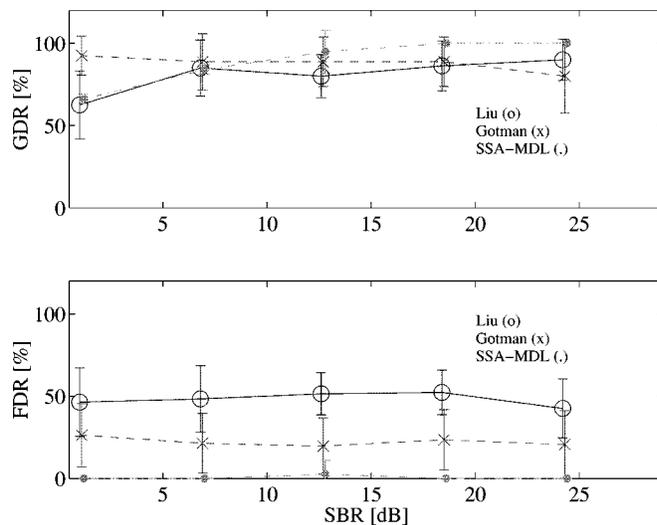


Fig. 5. Monte Carlo simulations for $1 \leq \text{SBR} \leq 24$ dB.

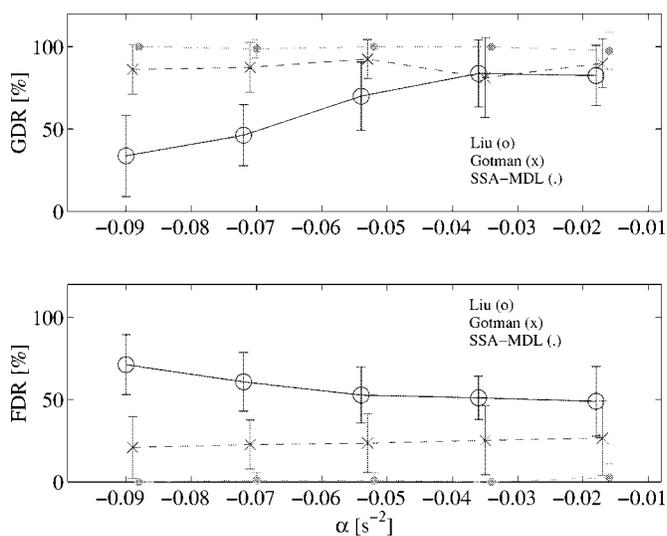


Fig. 6. Monte Carlo simulations for $-0.09 \leq \alpha \leq -0.018 \text{ s}^{-2}$.

For the SSA-MDL method, we still have to select n_s . Supposing that the bandwidth ΔB of seizure signals varies from 1 Hz to 5 Hz, we have $8 < n_s < 40$. In our experiments, we used $n_s = 20$ for all the parameters $\{\alpha, f_o, \text{SBR}, \text{SNR}\}$.

Figs. 5, 6, and Fig. 8 display the results with mean and standard deviations. Next, we will discuss each figure independently.

A. Mean Computation Time

The mean computation times³ required to run detection methods are 1.15 s for LIU, 9.06 s for GOTMAN, and 7.9 s for SSA-MDL. The LIU algorithm clearly outperforms the other methods. This is due to the fact that the Liu's method does not allow any overlap between sliding windows and to the reduced complexity of the detection algorithm. GOTMAN and SSA-MDL have comparable performances.

³We have used a Pentium III 700-MHz machine with 256-MB RAM, and implemented the detection methods in Matlab.

B. Signal-to-Background Ratio (SBR)

For this simulation, we fixed $f_o = 1.42$ Hz, $\alpha = -0.015$ s⁻², SNR= 11 dB, and varied SBR ($1 \leq \text{SBR} \leq 24$ dB). Results are shown in Fig. 5. We can observe that LIU has a lower mean GDR than GOTMAN and SSA-MDL for all SBR. Both LIU and SSA-MDL shows a drop in GDR for SBR < 7 dB while GOTMAN shows a re-markedly constant GDR. The SSA-MDL has a minimum GDR = 95%, but greater than GOTMAN for SBR ≥ 7 dB which is a far more smaller lower bound from our estimation of SBR on real data in Section III. LIU has the larger FDR, while GOTMAN has a greater FDR than SSA-MDL. With a maximum FDR = 2.6 %, SSA-MDL outperforms both LIU and GOTMAN. Standard deviations of GDR and FDR are almost the same for LIU and GOTMAN, while much greater than for SSA-MDL.

C. Linear FM Slope (α)

Fig. 6 was obtained by fixing $f_o = 1.42$ Hz, SBR =20 dB, and SNR= 11 dB and varying ($-0.09 \leq \alpha \leq -0.018$ s⁻²). GOTMAN method provides an almost constant GDR, while LIU shows a strong linear decrease in GDR when α becomes more negative. The GDR behavior for LIU can be explained by the fact that the autocorrelation function of a linear FM signal does not exhibit the expected regular T_1, \dots, T_4 intervals. As α decreases, the third and fourth peaks in the autocorrelation function tend to disappear. GOTMAN shows a greater or equal and almost constant GDR than LIU and much smaller FDR than LIU. The FDR for LIU increases significantly when α becomes more negative. SSA-MDL shows a better performance than both LIU and GOTMAN with a minimum GDR = 97%, while showing an increasing FDR for highly nonstationary seizure with a maximum FDR= 2.5%.

D. Frequency of the Seizure (f_o), for the Stationary Case

In this simulation, we fixed $\alpha = 0$ s⁻², SBR= 20 dB, SNR= 11 dB and varied f_o ($0.5 \leq f_o \leq 1.7$ Hz) to obtain results shown in Fig. 7. Both LIU and GOTMAN methods show a decrease in GDR when f_o is decreased. This effect can be explained by the increased bias and variance of the autocorrelation function (and thus of the power spectrum density) estimates for low frequencies (the processing window is constant for all frequencies). LIU shows a lower or equal GDR than GOTMAN in any cases. For LIU, the FDR shows a significant decrease when f_o is decreased, while GOTMAN shows an almost constant one. The FDR of LIU is larger than GOTMAN in any cases. SSA-MDL outperforms both LIU and GOTMAN with a constant GDR with a minimum of GDR = 94% and a maximum FDR = 2.6%.

E. Signal-to-Noise Ratio

In this experiment, we fixed $\alpha = -0.015$ s⁻², SBR= 20 dB, and $f_o = 1.42$ Hz and varied SNR ($5 \leq \text{SNR} \leq 17$ dB). The noise $n(t)$ is Gaussian and white. All the methods show an almost constant GDR and FDR. The GDR of LIU and GOTMAN are very similar (see Fig. 8). The FDR of LIU is much greater than the one of GOTMAN. SSA-MDL outperforms both LIU and GOTMAN with a constant GDR = 100% and a maximum FDR = 1.6 %.

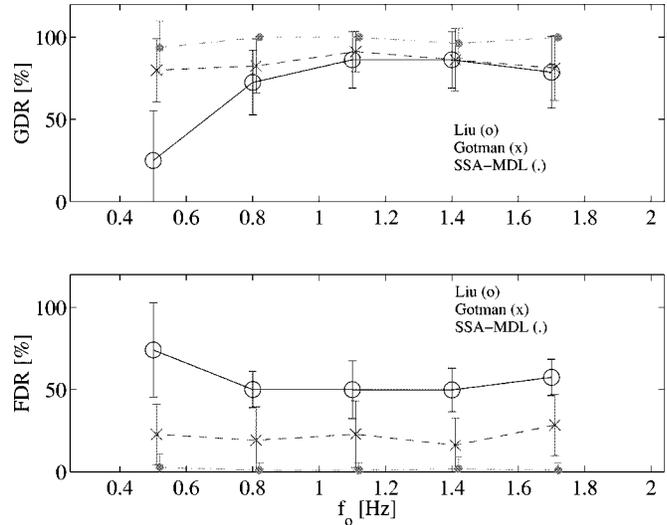


Fig. 7. Monte Carlo simulations for $0.5 \leq f_o \leq 1.7$ Hz.

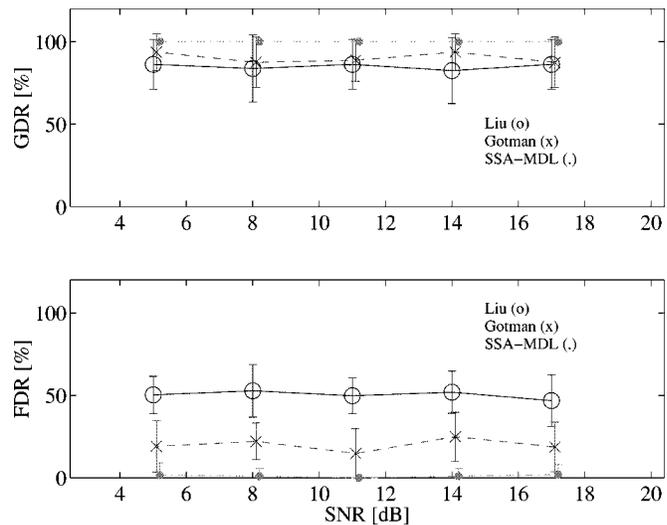


Fig. 8. Monte Carlo simulations for $5 \leq \text{SNR} \leq 17$ dB.

VI. PERFORMANCE COMPARISON ON EXPERIMENTAL DATA

Seizure detection should be performed on all the recorded channel because the spatial location of the seizure is *a priori* unknown. Nevertheless, we have selected by hand one channel where electrical seizures occurs, and run the different detection schemes on this channel. Multichannel detection should be used in practice by serial or parallel processing.

Table I shows the result of the three detection schemes on real newborns and infants EEG seizure signals. All the EEG signals were normalized to have zero-mean and unit variance for further processing. For a sake of comparison with the Monte Carlo, all the EEGs were also normalized to have a duration of $T = 8$ min. Additional background activity from the same recording was added at the beginning of the EEG channels to meet this requirement and not introduces artificial artifacts.

The LIU method shows an average GDR = 59% and an average FDR = 47%. The GOTMAN method shows an average GDR = 73% and an average FDR = 29%.

TABLE I
PERFORMANCE RESULTS ON REAL EEG DATA (a) LIU AND GOTMAN.
(b) SSA-MDL AND (SSA-MDL)_p

Baby Number	LIU		GOTMAN	
	GDR	FDR	GDR	FDR
1	63	35	73	21
2	54	45	68	23
3	68	52	79	32
4	51	58	73	41

(a)

Baby Number	SSA-MDL		(SSA-MDL) _p	
	GDR	FDR	GDR	FDR
1	85	4	80	12
2	96	6	85	14
3	97	3	90	7
4	95	5	92	15

(b)

The SSA-MDL column refer to the use of SSA-MDL with preprocessing, while SSA-MDL_p is without the use of the preprocessing. Results show that the FDR decrease drastically with the preprocessing especially for the baby number 4 for which large bursts of short EEG rhythmical activities were observed, thus increasing the non-Gaussianity of the signals, and affecting the FDR of all the methods. The SSA-MDL method shows an average GDR = 93% and an average FDR = 4 %.

While the GDR of all methods are smaller than using the Monte Carlo, they are still in the same relationship. The FDR of all the methods showed higher values on real data than using the Monte Carlo, especially on highly non-Gaussian signals. This result demonstrate the necessity of a preprocessing techniques prior to applying any detection methods.

VII. DISCUSSION

We proposed a new EEG seizure detection scheme based on SSA and a model order selection criterion originally developed by Rissanen. The use of the Rissanen's model selection criterion enabled us to design a data- and analysts-independent detector. Preprocessing the EEG using a recently proposed seizure model enable to use the MDL criterion in an optimal way, and to reduce the number of false alarms. Monte Carlo simulations on the three detection schemes have been performed. The results show the following.

- 1) The LIU method is computationally efficient.
- 2) The LIU method gives lower GDR and higher FDR than both SSA-MDL and GOTMAN.
- 3) The GOTMAN method is robust against SBR, while LIU and SSA-MDL are not for SBR < 6 dB. It is to be noted that SBR < 6 dB is quite unusual and have not been reported in our work.

- 4) LIU is very sensitive to the frequency f_o , while SSA-MDL and GOTMAN are more robust.
- 5) LIU is very sensitive to the nonstationarity parameter α , while GOTMAN and SSA-MDL are more robust.
- 6) All methods are robust against Gaussian white noise.

The most critical factor affecting the performances of the different schemes is the nonstationarity represented by α . This is not surprizing because all three methods are dedicated to stationary time series analysis even if they are processed by sliding windows. The proposed SSA-MDL detector has better performances in terms of GDR and FDR than the two other methods. The poorest performance of the SSA-MDL scheme has been achieved for the lowest SBR. One possible drawback of this method is the need to perform SVD decomposition on a trajectory matrix, hence limiting its application to off-line processing. To overcome this limitation, we have also proposed a real-time implementation of this method using adaptive algorithms [27], [28].

Results on real data show that SSA-MDL is a performant method compared with GOTMAN and LIU. The average GDR and FDR are lower than in the Monte Carlo, but still very good. The GDR of GOTMAN and SSA-MDL are quite comparable, but the very low FDR of SSA-MDL is a landmark of potential clinical assessment.

VIII. CONCLUSION

A new infant EEG seizure detection scheme based on SSA and model selection was presented. Using synthetic data, we were able to compare the performance of our method with that of two previously published techniques. Performance comparison was also conducted on a set of four infants showing signs of clinical and electrical seizures. The SSA-MDL method was shown to outperform the other two, especially in terms of FDR. Adaptive SSA-MDL is currently under investigation and should further improve the performance of the new detection scheme concerning both highly nonstationary environment and its real-time aspects.

Again, we would like to emphasize that the computer-based detection is a support for the clinician and does not provide the ultimate answer to the seizure detection problem, particularly for newborn and infant EEGs.

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