A Multi-version Approach to Conflict Resolution in Distributed Groupware Systems

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Abstract – Groupware systems are a special class of distributed computing systems which support human-computer-human interaction. Real-time collaborative graphics editors allow a group of users to view and edit the same graphics document at the same time from geographically dispersed sites connected by communication networks. Resolving conflict access to shared objects is one of the core issues in the design of this type of systems. This paper proposes a novel distributed multi-version approach to conflict resolution. This approach aims to preserve the work concurrently produced by multiple users in the face of conflicts, and to minimize the number of object versions for accommodating combined effects of conflicting and compatible operations. Major technical contributions of this work include a formal specification of a unique combined effect for any group of conflicting and compatible operations, a distributed algorithm for incremental creation of multiple object versions, and a consistent object identification scheme for multi-version and multi-replica graphics editing systems. All algorithms and schemes presented in this paper have been used in the GRACE (GRAphics Collaborative Editing) system implemented in Java.

Keywords
Collaborative graphics editors, consistence maintenance, multiple object versions, real-time groupware systems, distributed computing.

I. Introduction

Groupware systems are a special class of distributed computing systems which support human-computer-human interaction [2, 4, 13]. A commonly used groupware system is the real-time collaborative editor which allows a group of users to view and edit the same document at the same time from geographically dispersed sites connected by communication networks. Collaborative editors are very useful facilities in advanced Computer-Supported Cooperative Work (CSCW) applications [1], such as electronic conference/meeting, collaborative CAD/CASE, and collaborative documentation systems.

The goal of our research is to investigate the principles and techniques underlying the construction of collaborative editors with the following three major characteristics [13, 18]. (1) Real-time: The response to local user actions should be quick (without noticeable delay) and the latency for remote user actions should be low. The key performance parameter here is the response time observable by the user, rather than the number of operations per second as in non-interactive application systems. (2) Distributed: Collaborating users may reside on different machines connected by the Internet with non-negligible and non-deterministic latency. While there is no limit on the bandwidth increase of the Internet using fiber optic communication technologies, the communication latency over an inter-continental connection cannot be reduced considerably below 100 milliseconds (the threshold value for user noticeable delay) due to the speed limit of electronic signals. It is the communication latency, rather than the bandwidth, which presents a major challenge to achieving high responsiveness for Internet-based collaborative editing systems. (3) Unconstrained: Multiple users are allowed to concurrently and freely edit any parts of the document at any time, in order to facilitate free and natural information flow among collaborating users. The major challenge of supporting unconstrained collaborative editing is the management of the multiple streams of concurrent activities so that system consistency can be maintained in the face of conflicts.

The requirements for high responsiveness and for supporting unconstrained collaboration over the Internet have led us to adopt a replicated architecture for the storage of shared documents: the shared documents are replicated at the local storage of each participating site, so editing operations can be performed at local sites immediately and then propagated to remote sites. Because of concurrent generation of operations and non-negligible and non-deterministic communication latency of the Internet, there exist three major inconsistency problems associated with the replicated architecture [13]: (1) divergence - operations may arrive and be executed at different sites in different orders, resulting in different final documents at different sites; (2) causality violation – operations may arrive and be executed out of their natural cause-effect order, causing confusion to both the system and its users; and (3) intention violation – the actual effect of an operation at the time of its execution may be different from the intended effect of this operation at the time of its generation. To address these inconsistency problems systematically, a consistency model has been proposed in the context of the REDUCE (REal-time Distributed Unconstrained Cooperative Editing) project [13]. The REDUCE consistency model has been applied to the collaborative text editing domain for solving various challenging technical problems [14, 15, 16, 18]. In this paper, we will report new research findings in applying the REDUCE framework to the GRACE (GRAphics Collaborative Editing) project.

Collaborative graphics editing systems can be classified into two types: object-based and bitmap-based. This paper is confined to the issues associated with object-based collaborative graphics editing systems only. Graphic objects such as lines, rectangles, circles, etc., can be created and updated. Each object is represented by attributes such as type, size, position, color, group, etc. A Create operation is used to create an object. After an object has been created, updating operations can be applied to change the attributes of that object. For example, a Move operation changes the position attribute of the target object. In a collaborative editing environment, operation conflict may occur when multiple concurrent operations try to update the same object in different ways. Resolving conflict accesses to shared objects is one of the core issues in the design of this type of systems and will be the focus of this paper.

The rest of this paper is organized as follows. In Section II, some background information about the REDUCE framework is briefly discussed. In Section III, a multiple version strategy for conflict...
resonance is proposed, and the rules for determining combined effects of conflicting and compatible operations are derived. Then, a formal specification of a unique combined effect for any group of conflicting and compatible operations is presented in Section IV. A distributed algorithm for incremental creation of multiple object versions is described in Section V. A consistent object identification scheme for multi-version and multi-replica graphics editing systems is presented in Section VI. Our work is compared to related work in Section VII. Lastly, major results are summarized and further work is discussed in Section VIII.

II. Previous work

In this section, the basic concepts, definitions, and techniques adopted from our previous work are briefly described. For details, the reader is referred to [13].

A. A consistency model

Following Lamport [8], we define a causal (partial) ordering relation of operations in terms of their generation and execution sequences as follows.

Definition 1: Causal ordering relation “→”

Given two operations \( O_1 \) and \( O_2 \), generated at sites \( i \) and \( j \), then \( O_1 \rightarrow O_2 \), iff (1) \( i = j \) and the generation of \( O_1 \) happened before the generation of \( O_2 \), or (2) \( i \neq j \) and the execution of \( O_1 \) at site \( j \) happened before the generation of \( O_2 \), or (3) there exists an operation \( O_x \), such that \( O_1 \rightarrow O_x \) and \( O_x \rightarrow O_2 \).

Definition 2: Dependent and independent operations

Given any two operations \( O_1 \) and \( O_2 \), (1) \( O_2 \) is dependent on \( O_1 \) iff \( O_1 \rightarrow O_2 \). (2) \( O_1 \) and \( O_2 \) are independent (or concurrent), expressed as \( O_1 \| O_2 \), iff neither \( O_1 \rightarrow O_2 \), nor \( O_2 \rightarrow O_1 \).

Definition 3: Intention of an operation

Given an operation \( O \), the intention of \( O \) is the execution effect which could be achieved by applying \( O \) on the document state from which \( O \) was generated.

Definition 4: A consistency model

A collaborative editing system is said to be consistent if it always maintains the following properties: (1) Convergence: when all sites have executed the same set of operations, the copies of the shared document at all sites are identical. (2) Causality-preservation: for any pair of operations \( O_1 \) and \( O_2 \), if \( O_1 \rightarrow O_2 \), then \( O_1 \) is executed before \( O_2 \) at all sites. (3) Intention-preservation: for any operation \( O \), both the local and remote execution effects of \( O \) equal to \( O \)'s intention, and if there exists an operation \( O_x \), such that \( O_x \| O \), then the execution effect of \( O_x \) does not interfere with the execution effect of \( O \), and vice versa.

It should be highlighted that the consistency model imposes an execution order constraint only on dependent operations, but leaves it open for the execution order of independent operations as long as the convergence and intention-preservation properties are maintained. This feature of the consistency model lays the theoretical foundation for achieving good responsiveness by permitting local operations to be executed immediately after their generation. Moreover, the intention-preservation property makes a further promise to the users that their individual operations’ effects can be protected against each other’s interference. Finally, it should be pointed out that the three properties are independent in the sense that the maintenance of any two of them does not automatically ensure the other one [13, 14].

B. Concurrency control techniques

The consistency model specifies, on the one hand, what assurance a collaborative editing system promises to its users, and on the other hand, what properties the underlying concurrency control mechanisms must support. To capture the causal relationships among all operations in the system, a timestamping scheme based on vector logical clock can be used [13, 16]. Causality-preservation can be achieved by using either a distributed algorithm [13] or a central notification server [16]. Since causality is an issue without any relationship with the semantics of operations, causality-preservation techniques are generic and applicable to both text and graphics editors.

For supporting convergence and intention-preservation, however, different editing domains require different techniques. In the text editing domain, an optimistic concurrency control technique, called operational transformation has been devised [14]. In the GRACE project, convergence and intention-preserving techniques for the graphics editing domain have been investigated. Since achieving convergence is a relatively simple and independent issue, this paper will focus on the issues and results related to achieving intention-preservation only.

III. Operation conflicts and multiple versions

A. Conflict and compatible relations

In the graphics editing domain, concurrent operations may target the same object and may conflict with each other. For example, suppose user 1 generates operation \( O_1 = \text{Move}(G, X) \) to move object \( G \) to position \( X \), and user 2 concurrently generates operation \( O_2 = \text{Move}(G, Y) \) to move \( G \) to position \( Y \), where \( X \neq Y \). Both operations will be executed at their local sites immediately to give a quick response, and then propagated to the other sites. Since \( O_1 \) and \( O_2 \) are moving the same object \( G \) to two different positions, it is impossible to accommodate their conflicting effects in the same target object. In general, two concurrent operations are in conflict if they are targeting the same object but changing the same attribute to different values.

To give a precise definition of operation conflict, the following notations are introduced: (1) \( \text{Tgt}(O) \) denotes the target object of operation \( O \); (2) \( \text{Att.Type}(O) \) denotes the attribute type of \( O \); and (3) \( \text{Att.Value}(O) \) denotes the attribute value of \( O \).

Definition 5: Conflict relation “\( \circ \)”

Given two operations \( O_1 \) and \( O_2 \), they conflict with each other, expressed as \( O_1 \circ O_2 \), iff (1) \( O_1 \| O_2 \); (2) \( \text{Tgt}(O_1) = \text{Tgt}(O_2) \); (3) \( \text{Att.Type}(O_1) = \text{Att.Type}(O_2) \); and (4) \( \text{Att.Value}(O_1) \neq \text{Att.Value}(O_2) \).

In contrast, if a pair of operations are not conflicting, then they are compatible, as defined below.

Definition 6: Compatible relation “\( \odot \)”

Given two operations \( O_1 \) and \( O_2 \), if they do not conflict with each other, they are compatible, expressed as \( O_1 \odot O_2 \).

B. Accommodating all operation effects

For compatible operations, if they are targeting the same object, they can be applied to the same object. For conflicting operations,
what combined effects could they have without violating their intentions?

One possible combined effect is the **null-effect**, which means none of the two conflicting operations has any final effect on the target object. This can be achieved by rejecting/undoing an operation when it is found to be conflicting with another operation, as shown in Fig 1. The final results at both sites are identical (empty). However, this null effect does not preserve the intentions of the two operations since none of the two operations has any effect at the remote site and the effect of one operation has been undone by another independent operation. The consequence of this intention violation is that whenever there is a conflict, the work concurrently done by involved users will be destroyed. This effect is highly undesirable in the collaborative working environment because users involved in a conflict are provided with no explicit information about what other users intended to do, and hence may not be able to take proper actions to resolve their conflict.

![Fig. 1. The null-effect for conflicting operations](image)

The second possible combined effect is the **single-operation-effect**, which is to retain the effect of only one operation, either $O_1$ or $O_2$. This can be achieved by enforcing a serialized effect among all operations. As shown in Fig. 2, when $O_2$ arrives at user 1, it moves $G$ to position $Y$ (effectively undoing $O_1$); when $O_1$ arrives at user 2, it is rejected. The final results at both sites are identical. However, this single operation effect violates the intentions of both operations since one operation ($O_1$) has no effect at user 2, and the other operation ($O_2$) has changed the effect of an independent operation ($O_1$) at user 1. One consequence of this intention violation is that whenever there is a conflict, only one user’s work can be preserved. Another consequence is that users are not ensured to see the effects of the same set of operations: e.g., user 1 sees the effects of both $O_1$ and $O_2$, but user 2 never sees the effect of $O_1$.

Generally, when there are multiple conflicting operations, each user may see the effects of arbitrary number of operations, depending on the order in which operations arrive at each site. Therefore, when a conflict occurs, users may not see a consistent and explicit picture about what other users intended to do, and hence they may not be able to take proper actions to resolve their conflict.

To preserve all work concurrently produced by multiple users in the face of conflicts, we propose an **all-operations-effect** based on a multiple versions strategy: two versions of $G$, $G_1$ and $G_2$, will be created, with $O_1$ and $O_2$ being applied to $G_1$ and $G_2$, respectively. In this way, the effects of both operations are accommodated in two separate versions, as shown in Fig. 3.

This all-operations-effect preserves the intentions of both operations since the effects of $O_1$ and $O_2$ at their local sites are the same as their effects at the remote sites and they do not change the effects of each other. With this all-operations-effect, the system is able to ensure that the work produced by all users be always retained regardless whether there is a conflict or not. The only side effect of this approach is that the single version object may be converted to multiple versions if a conflict occurs. The system could notify the users that there is a conflict, e.g., by highlighting the multiple versions of the same object. Since all users are provided with a consistent and explicit picture about what other users intended to do, they could make better assessment of the situation and may decide to keep one of the versions or even all of them if that is desired.

![Fig. 2. Single operation effect for conflicting operations](image)

![Fig. 3. All operations effect for conflicting operations](image)

C. **Combined effect rules**

Given a group of $N$ operations targeting the same object, if they are all mutually compatible with each other, then they can be applied to the original target object without creating new versions; and if they are all mutually conflicting with each other, then $N$ versions can be created to accommodate each operation’s effect in a separate version. However, if there is a mixture of compatible and conflicting operations in the group, it becomes non-trivial to determine how many versions to create and how to apply which operations to which versions. In the following discussion, the notation $G\{O_k\}$ will be used to represent an object $G$ with the effect of $O_k$, and $G\{\}$ represents its initial state.

To start with, consider a simple scenario with three operations: $O_1$, $O_2$, and $O_3$. Suppose they are targeting the same object $G$, and their mutual conflict relations are: $O_1 \odot O_2$, $O_1 \odot O_3$, and $O_2 \odot O_3$. What combined effects should these three operations have?
Since \( O_1 \oplus O_2 \), they must be separately applied to two versions \( G\{O_1\} \) and \( G\{O_2\} \) according to the multiple versions strategy. In general, we have the following combined effect rule:

**Combined Effect Rule 1 (CER1):** Given two operations \( O_1 \) and \( O_2 \) targeting object \( G \). If \( O_1 \oplus O_2 \), they must be applied to different versions \( G\{O_1\} \) and \( G\{O_2\} \) made from \( G \).

The question is: how to combine \( O_2 \)'s effect? One possibility is to make a separate version \( G\{O_2\} \). The problem with this approach is that it unnecessarily creates two versions \( G\{O_1\} \) and \( G\{O_2\} \) for two compatible operations. To avoid unnecessary versions, we propose to combine two compatible operations \( O_2 \) and \( O_3 \) in a common version \( G\{O_2, O_3\} \). In general, to minimize the number of versions for an object, the following combined effect rule is used to justify the creation of different versions.

**Combined Effect Rule 2 (CER2):** Given any two versions \( G_1 \) and \( G_2 \) made from the same object \( G \), there must be at least one operation \( O_1 \) applied to \( G_1 \), and at least one operation \( O_2 \) applied to \( G_2 \), such that \( O_1 \oplus O_2 \).

Furthermore, consider another scenario with three operations: \( O_1, O_2, \) and \( O_3 \), targeting the same object \( G \). Suppose their mutual conflict relations are: \( O_1 \oplus O_2, O_1 \oplus O_3, \) and \( O_2 \oplus O_3 \). Since \( O_1 \oplus O_2 \), two versions \( G\{O_1\} \) and \( G\{O_2\} \) need to be created according to CER1. The question is: which one of the two versions should \( O_3 \) be applied to?

One possibility is to combine \( O_3 \) with either \( O_1 \) (i.e., \( G\{O_1, O_3\} \)) or \( O_2 \) (i.e., \( G\{O_2, O_3\} \)), chosen by the system (randomly or by using their total ordering). This approach does not produce any unnecessary version (according to CER2), but may have an abnormal phenomenon at the user interface, as shown in Fig. 4.

![Fig. 4. A scenario for motivating CER3](image)

Suppose the system has chosen to combine \( O_3 \) with \( O_1 \). At the site of user 3, the following abnormal phenomenon occurs: \( O_3 \) is first applied to its target object \( G \) to produce \( G\{O_3\} \); then \( O_2 \) arrives and is combined with \( O_3 \) to produce \( G\{O_2, O_3\} \) since they are compatible (site 3 has no knowledge about \( O_1 \) at this stage); finally \( O_1 \) arrives and is found to be conflicting with \( O_2 \), so \( O_3 \) has to be undone to produce \( G\{O_2\} \), and then redone in a new version to produce \( G\{O_2, O_3\} \) (to achieve the system chosen combined effect). In this scenario, user 3 will observe that \( O_1 \)'s effect is changing from one version to another version, due to the inconsistency between its initial effect and its final effect. This abnormal effect is undesirable, and also violates the intentions of operations since one operation (e.g., \( O_1 \)) changes (by undoing) the effect of another independent operation (e.g., \( O_3 \)). It should be pointed out that no matter which combined effect \( (O_3 \) combined with \( O_1 \) or \( O_2 \)) the system chooses, at least one user (user 1 or user 3) in this scenario will observe that the original execution effect of \( O_3 \) is undone and then redone in another object.

To avoid this abnormal interface effect, we propose to combine \( O_3 \) with both \( O_1 \) and \( O_2 \) to produce \( G\{O_1, O_3\} \) and \( G\{O_2, O_3\} \). In this way, no matter which orders these three operations are executed, the final combined effect will be the same at all sites, without any abnormal interface effect. In general, we have the following additional rule to determine the combined effects of compatible operations in the face of mixed compatible and conflict operations.

**Combined Effect Rule 3 (CER3):** Given any group of operations, if they are mutually compatible and target the same object, then their effects must be combined in at least one common version of the target object.

In summary, CER1, CER2 and CER3 are the three criteria for judging whether a combined effect for a group of operations targeting the same object is correct or not. By applying these criteria, the following combined effects can be achieved: (1) conflicting operations are accommodated in different versions; (2) compatible operations are combined in common versions; (3) there is at least one pair of conflicting operations between any pair of versions; and (4) there is at least one version combining the effects of any group of compatible operations.

**IV. Combined effects for any group of operations**

In the previous section, simple scenarios have been used to derive and illustrate the criteria (i.e., CER1, CER2 and CER3) to determine the combined effects of conflicting and compatible operations. However, in a highly concurrent real-time collaborative editing environment, a group of operations may have rather arbitrary and complex conflict relationships among them. A major technical problem here is: given an arbitrary group of operations targeting the same object, how to determine their combined effect, which is complying with CER1, CER2 and CER3?

**A. Conflict relation matrix and triangle**

To solve this problem, we first introduce the conflict relation matrix to capture the complete picture of conflict relationships among any group of operations targeting the same object.

Given a group of \( n \) operations, \( O_1, O_2, \ldots, O_n \), targeting the same object, their conflict relationships can be fully and uniquely expressed by a \( n \times n \) Conflict Relation Matrix (CRM), in which element \( CRM[i, j] \), \( 1 \leq i, j \leq n \) is filled with "\( \circ \)" if \( O_i \oplus O_j \), otherwise it is filled with "\( \Box \)". For example, a \( 3 \times 3 \) CRM for three operations is shown in Fig. 5-(a).

![Fig. 5. CRM versus CRT](image)

Since \( \circ \) and \( \oplus \) relations are symmetric (i.e., \( CRM[i, j] = CRM[j, i] \)), and an operation is always compatible with itself (i.e., \( CRM[i, i] = \circ \)), by omitting these redundant and constant relation elements, the conflict matrix can be compressed to a \( (n-1) \times (n-1) \) Conflict Relation Triangle (CRT). For example, the \( 3 \times 3 \) CRM in...
Fig 5-(a) can be compressed into an equivalent \( 2 \times 2 \) CRT in Fig. 5-(b).

### B. Compatible groups set

An alternative way of expressing the conflict/compatible relationships for a group of operations is called Compatible Groups Set (CGS), which is defined as follows.

**Definition 7:** Compatible Groups Set

Given a group of operations \( GO \), its corresponding Compatible Groups Set (CGS) is expressed as follows:

\[
CGS = \{ CG_1, CG_2, \ldots, CG_n \}
\]

where \( CG_i = \{ O_1, O_2, \ldots, O_\ell \} \), and (1) all operations in any \( CG_i \) must be mutually compatible; (2) for any operation \( O \in GO \), there must be at least one \( CG_i \in CGS \), such that \( O \in CG_i \); and (3) for any pair of operations \( O_\alpha, O_\beta \in GO \), if \( O_\alpha \cap O_\beta \), there must be at least one \( CG_i \in CGS \), such that \( O_\alpha, O_\beta \in CG_i \).

For example, the conflict relation expressed by the CRT in Fig. 5-(b) can also be captured by: \( CGS = \{ \{ O_1, O_2 \}, \{ O_3, O_4 \} \} \). In general, given a CRT, a CGS can be derived by using the following algorithm.

**Algorithm 1:** Given a CRT for a group of \( N \) operations \( GO \), a CGS corresponding to this CRT can be obtained as follows:

1. \( CGS = \{ \} \);
2. For \( 1 \leq i \leq N - 1 \), and \( i < j \leq N \), if \( CRT[i, j - 1] = \odot \)
   Then \( CGS = CGS + \{ \{ O_i, O_j \} \} \);
3. For \( 1 \leq i \leq N \), if \( O_i \notin CG_k \) for all \( k \in \{ 1, 2, \ldots, \} \),
   Then \( CGS = CGS + \{ \{ O_i \} \} \).

For example, as shown in Fig. 6, \( \{ O_2, O_3 \} \in CGS \) since \( CRT[2, 3 - 1] = \odot \), and \( \{ O_1 \} \in CGS \) since \( O_1 \) is not in any other \( CG \) in \( CGS \).

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<th>OP</th>
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Fig. 6. A CRT and its corresponding CGS.

It should be noted that in the CGS, the compatible relationships among operations are explicitly expressed by their co-existence in at least one \( CG \). However, the conflict relationships among operations are implicitly expressed by their non-coexistence in any \( CG \).

### C. Equivalent CGS

If two compatible groups sets \( CGS_1 \) and \( CGS_2 \) capture the same compatible relationships for the same group of operations, then they are equivalent, denoted as \( CGS_1 \equiv CGS_2 \). There exist some transformation rules which can be used to transform a CGS into another equivalent CGS.

In the following, we use the notation \( CG_i \odot CG_j \) to mean that all operations in both \( CG_i \) and \( CG_j \) are mutually compatible.

**Rule 1:** Given a CGS, for any pair \( CG_i, CG_j \in CGS \), if \( CG_i \not\subseteq CG_j, CG_j \not\subseteq CG_i \), and \( CG_i \odot CG_j \), then \( CGS \equiv CGS \setminus \{ CG_i, CG_j \} + \{ CG_i \cup CG_j \} \).

**Rule 2:** Given a CGS, if there exist \( CG_i, CG_j \in CGS \), \( i \neq j \), such that \( CG_i \subseteq CG_j \), then \( CGS \equiv CGS \setminus \{ CG_i \} \).

**Rule 2** says that if one group is a subgroup of another group in a CGS, then the subgroup can be removed.

### D. Normalized CGS

We are particularly interested in a special form of CGS, called Normalized Compatible Groups Set (NCGS), which is defined below.

**Definition 8:** Normalized Compatible Groups Set

Given a CGS for any group of operations \( GO \) targeting the same object, the CGS is a Normalized CGS (NCGS), iff: (1) for any group of mutually compatible operations in \( GO \), there must be at least one \( CG \in CGS \), such that all these compatible operations co-exist in \( CG \); and (2) for any pair \( CG_i, CG_j \in CGS \), there must be at least one \( O_\alpha \in CG_i \), and one \( O_\beta \in CG_j \), such that \( O_\alpha \odot O_\beta \).

By using Rules 1 and 2, a CGS can always be transformed into a NCGS. The following algorithm can be used to obtain a NCGS from a given CRT for any group of operations targeting the same object.

**Algorithm 2:** Given a CRT for a group of operations, a NCGS corresponding to this CRT can be obtained as follows:

1. Obtain a CGS for this CRT by using Algorithm 1.
2. Apply Rule 1 to transform CGS into CGS', so that all non-embracing but mutually-compatible groups are replaced by their unions.
3. Apply Rule 2 to transform CGS' into CGS", so that all subgroups are removed.
4. Return \( NCGS = CGS" \).

An example of applying Algorithm 2 to transform a CGS into a NCGS is given in Fig. 7.

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\[
CGS = \{ \{ O_1, O_2 \}, \{ O_1, O_3 \}, \{ O_2, O_4 \}, \{ O_2, O_3 \}, \{ O_3, O_4 \} \}
\]

\[
\equiv \{ \{ O_1, O_2, O_3 \}, \{ O_2, O_3, O_4 \} \} \text{ (by Rule 1)}
\]

\[
\equiv \{ \{ O_1, O_5, O_4 \}, \{ O_2, O_3, O_4 \} \} \text{ (by Rule 2)}
\]

\[
\equiv NCGS
\]

Fig. 7. A CRT, and its corresponding CGS and NCGS.
Furthermore, it is impossible for $G$ if $C_G$ with the following theorem establishes that this combined effect complies $CER_1$. If they are mutually compatible, they must coexist in at least one common operation, the $NCGS$ for this $GO$ is unique.

**Proof:** Suppose there are two $NCGS_1$ and $NCGS_2$ for the same $GO$. First, we prove that for $CG_x \in NCGS_1$, there must exist a $CG_x \in NCGS_2$, such that $CG_x = CG_y$. Since both $NCGS_1$ and $NCGS_2$ are for the same $GO$, all operations in $CG_x$ of $NCGS_1$ must also be in $NCGS_2$. Moreover, since all operations in $CG_x$ are mutually compatible, they must all be in at least one compatible group $CG_x$ in $NCGS_2$ according to Condition (1) of Definition 8. Furthermore, it is impossible for $CG_x$ to contain one extra compatible operation $O_y$. Otherwise, there must be at least one compatible group $CG_y$ in $NCGS_1$, which contains both $O_y$ and all operations in $CG_x$ according to Condition (1) of Definition 8. Thus, $CG_y$ must be subgroup of $CG_x$, which is contradicting to Condition (2) of Definition 8. Thus, $CG_x$ and $CG_y$ must contain the same group of compatible operations and hence $CG_x = CG_y$. By the same reasoning, it can be proven that for any $CG_y \in NCGS_1$, there must exists a $CG_x \in NCGS_1$, such that $CG_x = CG_y$. Thus the theorem follows. □

E. Combined effect specified by $NCGS$

The significance of the $NCGS$ is that it gives a formal specification of the combined effect for any group of operations targeting the same object.

**Definition 9:** $NCGS$ specified combined effect

Given the $NCGS$ for a group of operations $GO$ targeting object $G$, the combined effect for $GO$ is as follows: (1) For each $CG \in NCGS$, there is one object version made from $G$. (2) For all operations in the same $CG$, they will be applied to the same version corresponding to the $CG$.

The combined effect specified by the $NCGS$ is unique because the $NCGS$ for a group of operations $GO$ is unique. Furthermore, the following theorem establishes that this combined effect complies with $CER_1$, $CER_2$, and $CER_3$.

**Theorem 2:** The combined effects specified by the $NCGS$ satisfy $CER_1$, $CER_2$ and $CER_3$.

**Proof:** (1) For any pair of operations $O_i$ and $O_j$ in the $NCGS$, if $O_i \subset O_j$, they could never coexist in the same $CG$ in the $NCGS$ according to Condition (1) of Definition 7. and hence they could never be applied to the same object version, which complies with $CER_1$. (2) For any pair of compatible groups $CG_i$ and $CG_j$ in the $NCGS$, there must be at least one $O_x \in CG_i$, and one $O_y \in CG_j$, such that $O_x \subset O_y$ according to Condition (2) of Definition 8. Since there is one-to-one correspondence between the compatible groups in the $NCGS$ and the object versions made according to the $NCGS$ specified combined effect, $CER_2$ is satisfied. (3) For a group of operations, if they are mutually compatible, they must coexist in at least one common $CG$ according to Condition 1 of Definition 8, so they will be combined in at least one common object version, which complies with $CER_3$. □

In summary, the major result in this section is that given a group of operations targeting the same object, their combined effect can be uniquely determined by the $NCGS$, and this combined effect complies with $CER_1$, $CER_2$, and $CER_3$. The following sections will discuss how to achieve this unique and correct combined effect in a distributed, incremental, and consistent way.

V. Incremental creation of multiple versions

If the group of operations $GO$ targeting the same object are all known in advance, the $NCGS$ for this $GO$ can be constructed by using Algorithm 2; then multiple versions can be created and operations can be applied to proper versions according to the combined effects specified by the $NCGS$. However, in real-time collaborative editing sessions, operations can be generated concurrently and may arrive at different sites in different orders. Because of high responsiveness consideration, it is not proper (or feasible) to postpone executing an operation until all other potentially concurrent operations have arrived. An operation should be allowed to execute as long as it is in the right causal order. This means that the system has to execute the group of operations one after another to incrementally create versions (if necessary) and combine the effects of all operations. In other words, a distributed algorithm is needed to incrementally construct the $NCGS$ at all sites.

Suppose a group of $n$ operations targeting the same object arrive (and become causally ready for execution) at a site in the following order: $O_1, O_2, ..., O_n$. The algorithm will construct a sequence of $NCGS$: $NCGS_1, NCGS_2, ..., NCGS_n$ in such a way that $NCGS_1$ is the $NCGS$ for the group of operations from $O_1$ to $O_n$, and the final $NCGS_n$ is the $NCGS$ for the whole group of operations. To achieve this, two technical problems need to be solved: one is how to apply operation $O_i$ on $NCGS_{i-1}$ to produce $NCGS_i$; and the other is how to identify all object versions corresponding to $NCGS_{i-1}$ at each step. The second problem will be addressed in the next section. In this section, a Multiple Object Versions Incremental Creation (MOVIC) algorithm will be proposed to address the first problem.

A. The MOVIC algorithm

The following notations will be used in the description of the MOVIC algorithm: (1) $O_i$ represents the $i$th operation to execute at any site, (2) $NCGS_{i-1}$ represents the $(i-1)$th $NCGS$ for operations from $O_1$ to $O_{i-1}$. (3) $NCGS_i$ represents the $i$th $NCGS$ for operations from $O_i$ to $O_n$. (4) $O_i \subset CG$ means that $O_i$ is compatible with all operations in $CG$. (5) $O_i \subset CG$ means that $O_i$ is conflicting with all operations in $CG$.

The objective of the MOVIC algorithm is to apply $O_i$ to the $NCGS_{i-1}$ (i.e., to add $O_i$ to proper existing compatible groups in the $NCGS_{i-1}$ or to create new compatible groups if necessary) to produce the $NCGS_i$.

**Algorithm 3:** MOVIC($O_i, NCGS_{i-1})$ : $NCGS_i$

1. $NCGS_i := \{\}$; $C := [NCGS_{i-1}]$.
2. Repeat until $NCGS_{i-1} = \{\}$:
   (a) Remove one $CG$ from $NCGS_{i-1}$;
   (b) If $O_i \subset CG$, then $CG := CG + \{O_i\}$;
   (c) Else if $O_i \subset CG$, then $C := C - 1$;
   (d) Else
     $CG_{new} := \{O_i|O \in CG \land (O \subset O_i)\}$
     $CG_{new} := CG_{new} + \{O_i\}$
     $NCGS_i := NCGS_i + \{CG_{new}\}$
   (e) $NCGS_i := NCGS_i + \{CG\}$
3. If $C = 0$, then
   (a) $CG_{new} := \{O_i\}$
   (b) $NCGS_i := NCGS_i + \{CG_{new}\}$
4. For any $CG_{new} \in NCGS_i$, if there is another $CG \in NCGS_i$, such that $CG_{new} \subseteq CG$, then $NCGS_i := NCGS_i - \{CG_{new}\}$. □
In the MOVIC algorithm, the \( NCGS_1 \) is first initialized to an empty set, and \( C \) (a counter for the number of \( CGs \) which are not fully conflicting with \( O_i \)) is initialized to the size of the current \( NCGS_{i-1} \).

Then, \( O_i \) is checked against every \( CG \) in the \( NCGS_{i-1} \) one by one (Note: the order is not significant). If \( O_i \) is compatible with all operations in \( CG \), then \( O_i \) is added to \( CG \), which means that \( O_i \) can be directly applied to that object version. Else if \( O_i \) is conflicting with all operations in \( CG \), then \( O_i \) is not added to \( CG \), which means \( O_i \) cannot be applied to that object version. In this case, the counter \( C \) is decremented. Otherwise, \( O_i \) must be partially compatible with some operations in \( CG \). In this case, a new group \( CG_{new} \) is created, which contains all operations in \( CG \) which are compatible with \( O_i \), and then \( O_i \) is added to \( CG_{new} \), which means \( O_i \) is applied to a new object version corresponding to \( CG_{new} \). The newly created \( CG_{new} \) and the existing \( CG \) (with possibly an additional \( O_i \)) are still all added to the \( NCGS_i \). Since \( O_i \) is added only to groups with operations which are all compatible with \( O_i \), the resulting groups are ensured to be compatible groups (for Conditions 1 and 2 of Definition 7). Moreover, when \( O_i \) is compatible with multiple operations in an existing group, it is always added to that group or a new group containing all these compatible operations. In this way, Condition 1 of Definition 8 is satisfied.

After checking all \( CGs \) in the \( NCGS_{i-1} \), if \( C = 0 \), then \( O_i \) must be either the first operation (i.e., \( O_i = O_1 \)) or conflicting with all \( CGs \) in the \( NCGS_{i-1} \). In this case, a new group \( CG_{new} = \{ O_i \} \) is created (for Condition 2 of Definition 7).

A last but very important step in the MOVIC algorithm is to check each newly created group \( CG_{new} \) to see whether it is a subgroup of another group in the \( NCGS_i \). If this is the case, \( CG_{new} \) should be removed according to Rule 2 to ensure that there shall be at least one pair of conflicting operations in each pair of \( CGs \) in the new \( NCGS_i \) (for Condition 2 of Definition 8).

Since creating a new compatible group corresponds to creating a new object version, and adding \( O_i \) to an existing group or a new group corresponds to applying \( O_i \) to the object version for that group, it is straightforward to derive the method of executing \( O_i \) on the object versions corresponding to the \( NCGS_{i-1} \) as follows:

1. If \( O_i \) is added to an existing \( CG \) in Step 2-(b) of Algorithm 3, then \( O_i \) is applied to the existing object version corresponding to \( CG \).
2. If a \( CG_{new} \) is created out of an existing \( CG \) in Step 2-(d), and this \( CG_{new} \) is not removed in Step 4, then a new object version corresponding to \( CG_{new} \) is created and \( O_i \) is applied to it.
3. If a \( CG_{new} \) with only \( O_i \) is created in Step 3-(a), then a new object version corresponding to the \( CG_{new} \) is created and \( O_i \) is applied to it.

B. Order independency property

The MOVIC algorithm has a very important property: no matter in which orders a group of \( n \) operations are processed, the final \( NCGS \) constructed by the MOVIC algorithm is the same because there is only one unique \( NCGS \) for any group of operations (see Theorem 1). This property is called order-independency, which ensures that a consistent final result can be achieved at all collaborating sites regardless of different operation execution orders. A formal verification of this property is beyond the scope of this paper. Some examples are given below to illustrate the order-independency property.

Example 1: Given four operations \( O_1, O_2, O_3, \) and \( O_4 \), with their conflict relationships expressed in Fig. 8.

<table>
<thead>
<tr>
<th>OP</th>
<th>( O_2 )</th>
<th>( O_3 )</th>
<th>( O_4 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( O_1 )</td>
<td>( \square )</td>
<td>( \square )</td>
<td>( \square )</td>
</tr>
<tr>
<td>( O_2 )</td>
<td>( \square )</td>
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<td>( \square )</td>
</tr>
<tr>
<td>( O_3 )</td>
<td>( \square )</td>
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</tbody>
</table>

Fig. 8. The CRT for Example 1

Consider the following two different execution orders:

**Execution Order 1:** \( O_1, O_2, O_3, \) and \( O_4 \).
1. \( NCGS_1 = \{ \{ O_1 \} \} \)
2. \( NCGS_2 = \{ \{ O_1, O_2 \} \} \)
3. \( NCGS_3 = \{ \{ O_1, O_2, O_3 \} \} \)
4. \( NCGS_4 = \{ \{ O_1, O_4 \}, \{ O_2, O_4 \}, \{ O_3, O_4 \} \} \)

**Execution Order 2:** \( O_1, O_2, O_4, \) and \( O_3 \).
1. \( NCGS_1 = \{ \{ O_1 \} \} \)
2. \( NCGS_2 = \{ \{ O_1, O_2 \} \} \)
3. \( NCGS_3 = \{ \{ O_1, O_2, O_4 \} \} \)
4. \( NCGS_4 = \{ \{ O_1, O_4 \}, \{ O_2, O_4 \}, \{ O_3, O_4 \} \} \) (by Rule 2)

It can be seen that at Step 4 of Execution Order 2, \( O_3 \) is first checked against \( \{ O_1, O_4 \} \) and a new group \( \{ O_4, O_3 \} \) is created since \( O_4 \cap O_3 \) but \( O_1 \cap O_3 \); then \( O_3 \) is checked against \( \{ O_2, O_4 \} \) and another (exactly the same) new group \( \{ O_2, O_3 \} \) is created for the same reason. However, one of the two new groups is removed according to Rule 2. In this way, the final \( NCGS \) is the same for two different execution orders.

Example 2: Given four operations \( O_1, O_2, O_3, \) and \( O_4 \), with their conflict relationships expressed in Fig. 9.

<table>
<thead>
<tr>
<th>OP</th>
<th>( O_2 )</th>
<th>( O_3 )</th>
<th>( O_4 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( O_1 )</td>
<td>( \square )</td>
<td>( \square )</td>
<td>( \square )</td>
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<tr>
<td>( O_2 )</td>
<td>( \square )</td>
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<td>( \square )</td>
</tr>
<tr>
<td>( O_3 )</td>
<td>( \square )</td>
<td>( \square )</td>
<td>( \square )</td>
</tr>
</tbody>
</table>

Fig. 9. The CRT for Example 2

Consider the following two different execution orders:

**Execution Order 1:** \( O_1, O_2, O_3, \) and \( O_4 \).
1. \( NCGS_1 = \{ \{ O_1 \} \} \)
2. \( NCGS_2 = \{ \{ O_1, O_2 \} \} \)
3. \( NCGS_3 = \{ \{ O_1, O_2, O_3 \} \} \)
4. \( NCGS_4 = \{ \{ O_1, O_4 \}, \{ O_2, O_4 \}, \{ O_3, O_4 \} \} \) (by Rule 2)

**Execution Order 2:** \( O_1, O_2, O_4, \) and \( O_3 \).
1. \( NCGS_1 = \{ \{ O_1 \} \} \)
2. \( NCGS_2 = \{ \{ O_1, O_2 \} \} \)
3. \( NCGS_3 = \{ \{ O_1, O_2, O_4 \} \} \)
4. \( NCGS_4 = \{ \{ O_1, O_4 \}, \{ O_2, O_4 \}, \{ O_3, O_4 \} \} \) (by Rule 2)

As shown in Step 4 of Execution Order 2, when \( O_3 \) is first checked against \( \{ O_1, O_4 \} \), a new group \( \{ O_4, O_3 \} \) is created since \( O_4 \cap O_3 \) but \( O_1 \cap O_3 \); then \( O_3 \) is checked against \( \{ O_2, O_4 \} \), and is
added into this existing group (becoming \{O_2, O_4, O_5\}) since \(O_3\) is compatible with all operations in this group. However, the new group \(\{O_4, O_5\}\) is removed since it is a subgroup of \(\{O_2, O_4, O_5\}\) according to Rule 2. In this way, the final \(NCGS_4\) is the same for two different execution orders.

VI. Consistent object identification

For the MOVIC algorithm to work, one important parameter has to be provided: the current \(NCGS_{i-1}\), on which the new operation \(O_i\) is applied to produce \(NCGS_i\). The technical issue here is: how to find the \(CGs\) in the \(NCGS_{i-1}\) for \(O_i\)? Since a \(CG\) in the \(NCGS_{i-1}\) corresponds to an object version made from the original object targeted by \(O_i\), the above issue is converted into the question: how to find the object versions made from the original object targeted by the new operation \(O_i\)? The key to solving this problem is to devise an object identification scheme which is able to identify all object versions made from the same original object.

A. Requirements for object identification

To work in a multi-version and multi-replica (due to replicated architecture for the storage of shared documents) object-based graphics editing system, the object identification scheme must maintain the following three properties: (1) Uniqueness: every object at a site must have a unique identifier. (2) Traceability: multiple versions of the same object must have identifiers which can be traced by using the identifier of \(G\). (3) Consistency: multiple replicas of the same object at different sites must have the same identifier.

The uniqueness property ensures different objects at a site be distinguishable from each other. The traceability property ensures multiple versions of the same object be traceable by using the identifier of the original object. The consistency property ensures multiple replicas of the same object have the same identifier so that operations applied on one replica be also applied the other replicas. The three properties together ensure that an operation targeting an object be applied to all versions and all replicas of the same object at all sites.

B. Analysis of object identification issues

We start from a simple object identification scheme which is able to uniquely identify every object. Let \(Id(G)\) denote the identifier of object \(G\). Suppose each operation \(O\) has a unique identifier, denoted as \(Id(O)\)^2. Then, each object can be uniquely identified by the identifier of the operation which created this object. Under this scheme, when object \(G\) is created by operation \(O\) at a local site, \(G\) is assigned a unique identifier which is equal to \(Id(O)\), i.e., \(Id(G) = Id(O)\). When \(O\) is propagated to a remote site, a replica of the same object will be created and assigned the same identifier. When a non-create operation \(O\) is applied to an existing object \(G\) at the local site, \(O\) will take \(Id(G)\) as one of its parameters (i.e., \(Tgt(O) = Id(G)\)). When \(O\) arrives at a remote site, its parameter \(Tgt(O)\) can be used to find the right replica of the same object to apply. This simple identification scheme works well for simple version systems, but fails when multiple versions of the same object can be created due to operation conflicts.

For example, consider three operations \(O_1, O_2,\) and \(O_3\), targeting the same object \(G\). Suppose their conflict relationships are: \(O_1 \cap O_2, O_1 \cap O_3,\) and \(O_2 \cap O_3.\) Assume these three operations are executed at a site in the order of \(O_1, O_2,\) and \(O_3.\) To execute \(O_1\), the target object \(G\) can be found by its original identifier \(Id(G)\) (= \(Tgt(O_1)\)). To execute \(O_2\), the target object \(G\) can still be found by \(Id(G) (= Tgt(O_2))\) because the previous execution of \(O_1\) does not change the identifier of \(G\). However, after executing both \(O_1\) and \(O_2,\) two versions \(G\{O_1\}\) and \(G\{O_2\}\) have been made from \(G\) and the original \(G\) disappeared. When \(O_3\) arrives with \(Tgt(O_3) = Id(G),\) both \(G\{O_1\}\) and \(G\{O_2\}\) must be found in order to combine \(O_3\)’s effect with them. The question is: how should \(G\{O_1\}\) and \(G\{O_2\}\) be identified so that they can be traced by using \(Id(G)\)?

To address the multiple versions identification problem, the simple identification scheme can be extended (1) to let both versions inherit the identifier of the original object so that they are traceable by using \(Id(G)\); and (2) to let one version include one additional identifier of the operation which triggers the creation of that new version so that multiple versions are distinguishable from each other.

In this example, since \(O_2\) triggers the creation of a new version, \(G\{O_2\}\) could simply take the identifier of \(G,\) i.e., \(Id(G\{O_2\}) = Id(G),\) but \(G\{O_2\}\) will take \(Id(G) + Id(O_2)\) as its identifier, i.e., \(Id(G\{O_2\}) = Id(G) + Id(O_2)\) (the precise meaning of “+” will become clear at the end of this subsection). Clearly, \(Id(G\{O_1\}) \neq Id(G\{O_2\})\), and both \(G\{O_1\}\) and \(G\{O_2\}\) are traceable by using \(Id(G)\) since \(Id(G)\) is included in both \(Id(G\{O_1\})\) and \(Id(G\{O_2\})\).

The above extended identification scheme is able to ensure multiple versions of the same object be distinguishable from each other and traceable from the identifier of the original object. However, it is not able to ensure consistency of the identifiers of multiple replicas of the same object. To illustrate this problem, assume the two conflicting operations in the previous example are executed at a different site in a different order: \(O_2\) followed by \(O_1.\) In this scenario, it will be \(O_1\) which triggers the creation of a new version, so \(G\{O_1\}\) will take \(Id(G) + Id(O_1)\) as its identifier, but \(G\{O_2\}\) will simply take the identifier of \(G,\) i.e., \(Id(G\{O_2\}) = Id(G).\) Clearly, the two replicas of the same object \(G\{O_2\}\) have been identified differently when the two conflicting operations are executed in different orders.

To solve this problem, the previous identification scheme is revised to let both versions include one additional identifier of the corresponding conflicting operation. For the previous example, \(G\{O_1\}\) should take \(Id(G) + Id(O_1)\) as its identifier, i.e., \(Id(G\{O_1\}) = Id(G) + Id(O_1);\) and \(G\{O_2\}\) should take \(Id(G) + Id(O_2)\) as its identifier, i.e., \(Id(G\{O_2\}) = Id(G) + Id(O_2).\) With this revised scheme, no matter in which order conflicting operations are executed, multiple replicas of the same object version will be identified consistently.

The object identification scheme would not be completely correct if the following more subtle inconsistency scenario was not discovered and resolved. Given three operations: \(O_1, O_2,\) and \(O_3\) targeting the same object \(G.\) Suppose their conflict relationships are: \(O_1 \cap O_2, O_1 \cap O_3,\) and \(O_2 \cap O_3.\) First, consider the outcome of executing these operations in the order of \(O_1, O_2,\) and \(O_3.\) After executing \(O_1,\) \(G\) becomes \(G\{O_1\}\), but \(Id(G\{O_1\}) = Id(G).\) After executing \(O_2,\) a new version \(G\{O_2\}\) is created and is identified by \(Id(G\{O_2\}) = Id(G) + Id(O_2).\) In the meanwhile, another version \(G\{O_1\}\) is identified by \(Id(G\{O_1\}) = Id(G) + Id(O_1)\) according to the revised identification scheme. Finally, when \(O_3\) arrives, it will be applied to the existing versions \(G\{O_2\}\) directly since \(O_3 \cap O_2.\) The final outcome of executing the three operations will be two versions: \(G\{O_1\}\) with an identifier of \(Id(G) + Id(O_1)\), and \(G\{O_2, O_3\}\) with an identifier of \(Id(G) + Id(O_2)\). However, if the three operations are executed at a different site in a different order: \(O_1, O_2,\) and \(O_3,\) the final outcome of executing the three operations will also be two versions: \(G\{O_1\}\) with an identifier of \(Id(G) + Id(O_1)\), and \(G\{O_2, O_3\}\) with an identifier of \(Id(G) + Id(O_2)\).
\(Id(O_1)\) (because \(O_1\) triggers the creation of \(G[O_1]\)). Clearly, the two replicas of the same object version \(G[O_1, O_2]\) are identified by two different identifiers (i.e., \(Id(G) + Id(O_1)\), and \(Id(G) + Id(O_2)\))!

In recognizing this problem, the previous object identification scheme is further revised to let a version’s identifier include the identifiers of all operations (e.g., both \(O_1\) and \(O_2\)) which are conflicting with another operation (e.g., \(O_i\)), regardless which operation triggers the creation of this new version. Furthermore, it becomes clear that the collection of operation identifiers in the object identifier should be treated as a set, rather than a list. In a set representation, the order of adding a conflicting operation identifier into the object identifier is not significant.

### C. The COID scheme

Based on the above analysis, a Consistent Object IDentification (COID) scheme is defined below.

**Definition 10:** The COID scheme

The identifier of object \(G\) consists of a set of operations identifiers:

\[
Id(G) = \{ Id(O_1), Id(O_2), \ldots, Id(O_n) \},
\]

where \(Id(O_i) \in Id(G), 1 \leq i \leq n, \text{ iff } (1) O_i \text{ is the operation which created } G, \text{ or } (2) O_i \text{ has been applied to } G, \text{ and } O_i \text{ is conflicting with an operation } O_x, \text{ which has been applied to another version made from } G.

In the context of the MOVIC algorithm, the COID scheme can be realized as follows:

1. When operation \(O\) creates an original object \(G\), \(Id(G)\) is constructed as follows: \(Id(G) := \{Id(O)\}\).
2. When operation \(O\) triggers the creation of a new version \(G’\) from the target object \(G\), \(Id(G’)\) is constructed as follows: \(Id(G’) := Id(G) + \{Id(O)\}\).
3. When operation \(O\) is applied to an existing object \(G\), \(Id(G)\) is extended to include \(Id(O)\) if \(O\) is conflicting with any other operation (in \(G\) or in any other version).
4. When operation \(O\) is applied to one version of object \(G\), every other version of \(G\), denoted as \(G^x\), is checked to see whether \(G^x\) has the effect of an operation \(O_x\), such that \(O_x \bigodot O\). If there exists such an \(O_x\) and \(Id(O_x)\) has not been included in \(Id(G^x)\), then \(Id(G^x)\) is extended as follows: \(Id(G^x) := Id(G^x) + \{Id(O_x)\}\).

The COID scheme maintains the *uniqueness* property because the \(Create\) operation is unique, and any two versions of the same object must have at least one pair of conflicting operations. Moreover, the COID scheme maintains the *consistency* property because for an object, the same set of versions will be replicated at all sites (due to the uniqueness property of the NCGS), and conflict relationships among all operations are the same at all sites. Finally, the COID scheme maintains the *traceability* property because the identifiers of all versions of the same object \(G\) are supersets of \(Id(G)\). To answer the question raised at the beginning of this section, the following Target Object VVersion Recognition (TOVER) scheme is defined.

**Definition 11:** The TOVER scheme

Given any operation \(O_i\), any object \(G\) is a version corresponding to a compatible group \(CG\) in the current \(NCGS_{\text{all}}\) iff \(T \not\in (O_i) \subseteq Id(G)\). 

### VII. Comparison to related work

Most existing collaborative graphics editing systems have adopted a conflict-prevention approach based on locking. Example systems based on locking include: Aspects [17], Ensemble [11], GroupDraw [3], and GroupGraphics [12]. In these systems, a user has to place a lock on an object before editing it, thus preventing other users from generating conflicting operations on the same object. For locking to work, however, there has to be a coordinating process in the system which keeps track of which object(s) has been locked so it can grant/deny permissions for locking requests. The problem with locking is that when an editing operation is generated, it has to wait for at least a round trip time of sending a request message to the coordinating process and receiving a grant message back, before it can be executed (if it is allowed) at the local site. This round trip delay in the Internet environment may significantly degrade the system’s responsiveness. Various techniques have been proposed to overcome this problem. For example, Ensemble allows conflict-free operations to execute immediately without waiting for approval. While in GroupDraw, locally generated operations are executed right away and a message is sent to the coordinating process. If the coordinating process does not approve the operation, then the effect of that operation is undone, which may cause abnormal phenomena at the user interface.

In contrast to conflict-prevention approaches like locking, the multi-version strategy proposed in this paper allows conflict to occur. It provides a mechanism (i.e., multiple object versions) to accommodate conflicting operations in a consistent way. Conflict resolution is left to the users. Major advantages of this approach are: it helps achieve high responsiveness of the system and preserve the work concurrently produced by multiple users in the face of conflicts. However, locking does have its merit of reducing conflicts by enforcing mutual exclusion. In fact, we have found locking is actually complementary and compatible with the optimistical concurrency control strategies and proposed a novel *optional locking* scheme (in contrasting to existing compulsory locking schemes) to enhance the consistency maintenance capability of the system [15]. Our investigation into the integration of this optional locking scheme with the multi-version approach in the graphics editing domain will be reported in a forthcoming paper.

Another alternative conflict-resolution approach is *serialization*. With this approach, operations can be executed as soon as they are generated to give a quick response. Before an operation is executed, it must be checked against executed operations for possible conflict. If a conflict is detected, a total ordering (i.e., serialization) between operations is used to determine which operation’s effect will appear. Examples of such systems are: GroupDesign [7] and LICRA [5]. This approach is essentially the *single-operation-effect* (determined by a total ordering) approach discussed in Section III. For problems with this approach and its major differences with our *all-operations-effect* approach, please refer to the analysis in Section III.

The most closely related work is the Tivoli whiteboard meeting-supporting tool developed at Xerox PARC [9]. Tivoli also used multiple object versions (called *replicas* in Tivoli) to accommodate the effects of conflicting operations. The major difference between the Tivoli approach and our GRACE approach is that in Tivoli conflict is defined at the object level, i.e., a conflict occurs whenever two concurrent operations target the same object; whereas in GRACE, conflict is defined at object attribute level, i.e., a conflict occurs only when two concurrent operations target the same object and change the same attribute to different values. Consequently, Tivoli does not allow compatible operations (according to GRACE conflict definition) to be applied to the same object (e.g., concurrent *Move* and *Fill*).
operations cannot be applied to the same object), resulting in unnecessary object versions. To our knowledge, the GRACE system is the only one in which operation conflict is defined at the object attribute level to minimize the number of object versions. Consequently, the technical issues and solutions reported in this paper are unique and have never been addressed by any other work.

VIII. Conclusions and future work

In this paper, we have proposed a novel multi-version approach to conflict resolution in real-time collaborative graphics editing systems. This approach is able to preserve the work concurrently produced by multiple users in the face of conflicts, and to minimize the number of object versions for accommodating combined effects of conflicting and compatible operations. Major technical contributions of this work include a formal specification of a unique combined effect for any group of conflicting and compatible operations, a distributed algorithm for incremental creation of multiple object versions, and a consistent object identification scheme for multi-version and multi-replica graphics editing systems.

All algorithms and schemes presented in this paper have been implemented in the Internet-based GRACE prototype system in Java. The current GRACE prototype system has been developed mainly to test the feasibility of our approach and to explore system design and implementation issues. Efforts are being directed towards building a more robust and useful system, which will be used by external users in real application contexts to evaluate the research results from end-users’ perspective.

The multi-version approach alone is not a complete solution to resolving conflicts in collaborative systems. Other complementary techniques should be integrated to work in conjunction with the multi-version technique. We are in the process of devising a group awareness mechanism and an optional locking scheme to help minimize the chance of conflict. Work is underway to apply GRACE techniques to other advanced object-based graphics editing systems as well.

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References